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Academy of Sciences of the Czech Republic Institute of Information Theory and Automation

## RESEARCH REPORT

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## A causal model of price and volume on market with a market maker

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## 1 Introduction

One of the key roles in price formation at today's financial markets is played by market makers (MMs) - agents who are obliged to set buying and selling qoutes (bid and ask) and trade for the prices they set. Clearly, as other economic agents, MMs are profit maximizers. The economic analysis of their behariour is, however, quite complicated since the decision problems they face are dynamic by nature hence intractable (see[2] and the citation therein).

In the present paper, we suggest a rather simple version of such a decision problem. In particular, we assume the MM to maximizehis discounted consumption while keeping the probability of the bancrupcy (i.e. running out of the money or the traded asset) at a prescribed, perhaps very small level. We do not give analytic solution of the problom but we prove that the prices set by the MM depend - out of all the past information - only on the amount of the asset held by MM and on his uncertainty concerning the fair price.

After a nomral approximation of (Compound Poisson) bought and sold anounts of an asset we are able to determine a distribution of the process of midpoint prices and the inventory of the MM (i.e. total number of assets held) which we, after a local linearization of optimal strategies, validate by means of ten seconds high frequency data and estimate its parameters. As we used OLS, our estimates are both consistent and asyptotically normal. We also show a benchmark models assuming irrationality of the MM's and/or the liquidity takers, may be rejected in favour of our model.

## 2 The setting

Let there be two types of agents: the market makers posting quotes (the best bid and ask), and the informed traders.

In our model, there is a single (representative) market maker, i.e., agent who, at each $t \in \mathbb{N},{ }^{1}$ sets the log-quotes $a_{t}$ and $b_{t}$ (the actual best ask and best bid are then $A_{t}=e^{a_{t}}, B_{t}=e^{b_{t}}$, respectively) in order to maximize their discounted overall consumption.

In reaction to the quotes, the traders post market orders, i.e. requests to buy or to sell a certain amount of the asset for the ask price, bid price, respectively. The numbers of buy and sell market orders arrived from time $t-1$ to $t$, are Poisson with intensities depending solely on a distance of the corresponding log-quote to a log-fair price $\pi_{t} \in \mathbb{R}$, in particular, the intensities are

$$
\lambda\left(a_{t-1}-\pi_{t-1}\right), \quad \lambda\left(\pi_{t-1}-b_{t-1}\right)
$$

respectively where

$$
\lambda(z)=\left\{\begin{array}{ll}
r(1-z / D) & z \leq D \\
0 & z>D
\end{array}, \quad r>0, \quad D>0\right.
$$

The sizes of the orders are random, with common distribution $\mathcal{P}$, independent each on other and on the numbers of the order arrived. We denote $\mu$ the mean and $s$ the raw second moment of $P$ (i.e. the variance of $\mathcal{P}$ is $s-\mu^{2}$ ).

The (log)fair price $\pi$ follows a possibly non-normal non-homogenous random walk with

$$
\mathbb{E} \Delta \pi_{t}=0
$$

We distinguish three possible degrees of information, available to the MM:
(I) The MM is fully informed, i.e. the values of $\pi$ are observable to him

[^0](P) The MM is partially informed, i.e. he observes a proxy
$$
e_{t}=\pi_{t}+\zeta_{t}
$$
for some $\zeta_{t}, \mathbb{E}\left(\zeta_{t}\right)=0$
(U) The MM is uninformed.

Denoting $X_{t+1}$ and $Y_{t+1}$ the total volume of the buy market orders, sell market orders, respectively, which have arrived since $t$ to $t+1$, and denoting

$$
\begin{equation*}
\Xi_{t}=\left(\pi_{0}, X_{1}, Y_{1}, e_{1}, \pi_{1}, \ldots, X_{t}, Y_{t}, e_{t}, \pi_{t}\right) \tag{1}
\end{equation*}
$$

all the (historical) information relevent for the market (given ( I ), we can put $e_{t}=\pi_{t}$, given ( U ), we can assume an infinite variance of $e_{t}$ by definition), our setting may be formally described as follows:
(D1) $X_{t} \mid \Xi_{t} \sim \operatorname{CP}\left(\lambda\left(a_{t-1}-\pi_{t-1}\right), \mathcal{D}\right)$,
(D2) $Y_{t} \mid \Xi_{t-1}, \sim \operatorname{CP}\left(\lambda\left(\pi_{t-1}-b_{t-1}\right), \mathcal{D}\right)$,
(I1) $\Delta \pi_{t}, \zeta_{t}$ and $\left(\Xi_{t-1}, X_{t}, Y_{t}\right)$ are mutually independent.
(I2) $X_{t}$ is conditionally independent of $Y_{t}$ given $a_{t-1}-\pi_{t-1}, \pi_{t-1}-b_{t-1}$
Here, $\mathrm{CP}(\kappa, \mathcal{Q})$ denotes the compound Poisson distribution with intensity $\kappa$ and summands' distribution $\mathcal{Q}$.

Note that the functions $\bar{d}(p)=\mu \kappa\left(p-\pi_{t}\right)$ and $\bar{s}(p)=\mu \lambda\left(\pi_{t}-p\right)$, are equal to the expected volumes of buy market orders, sell market orders, respectively, arriving between $t$ and $t+1$; therefore, $\bar{d}$ and $\bar{s}$ may be interpreted as (expected) demand curve, supply curve, respectively. Moreover, since

$$
\pi_{i}=\arg \max _{p}[\bar{d}(p) \wedge \bar{s}(p)]
$$

we may regard $\pi_{t}$ as the equilibrium price. The expected overall traded volume between $t$ and $t+1$ is then given by

$$
R=\bar{d}\left(\pi_{t}\right)=\bar{s}\left(\pi_{t}\right)=\mu r ;
$$

thus, constant $R$ may be called preliquidity. Finally, as

$$
\bar{d}(p) \wedge \bar{s}(p) \geq 0 \Leftrightarrow p \in\left(\pi_{t}-D, \pi_{t}-D\right)
$$

the parameter $D$ may be named prespread.

## 3 The MM's decision problem

Let us turn out to the study of the MM holding $M_{0}$ units of cash and $N_{0}$ units of the traded asset at the time 0 . Denote $C_{t}$ the MM's consumption at $t$. Naturally, the increments of the cash holding, asset holding, respectively, are

$$
\begin{equation*}
\Delta M_{t}=e^{a_{t-1}} X_{t}-e^{b_{t-1}} Y_{t}-C_{t-1}, \quad \Delta N_{t}=Y_{t}-X_{t}, \quad t>0 \tag{2}
\end{equation*}
$$

We assume that the consuption $C_{t}$ may be also negative, i.e. it is allowed to MM to "put its own money into the bussiness" if needed. Moreover, we allow the MM to borrow stocks for a single period.

As we have already premised, we assume the MM to maximize his discounted consumption at a time $t$ so that both the probability of running out of the money (i.e. a negative $M_{t+1}$ ) and the probability of depleeting the asset (i.e. a negative $N_{t+1}$ ) is less than a prescribed level.

As the MM possibly does not know the values of the fair price, his information set at the time $t$ consists of

$$
\xi_{t}=\left(e_{1}, X_{1}, Y_{1}, e_{2}, X_{2}, Y_{2}, \ldots e_{t}, X_{t}, Y_{t}\right)
$$

where $e_{t}=\pi_{t}$ in case of (I) and $e_{t}$ has an infinite variance by definition in case of (U).
Definition 1. The decision problem, solved by the MM at each $t \in \mathbb{N} \cup\{0\}$, is given by

$$
\begin{equation*}
V_{t}\left(\xi_{t}\right)=\sup _{a_{\tau}, b_{\tau}, C_{\tau}, t \leq \tau \leq T} \mathbb{E}\left[\sum_{\tau=t}^{T-1} e^{-\rho(\tau-t)} C_{\tau}+e^{-\rho(T-t)}\left(M_{T}+e^{\pi_{T}} N_{T}\right) \mid \xi_{t}\right] \tag{3}
\end{equation*}
$$

such that, for all $t \leq \tau<T$,

\[

\]

$$
\tau \geq t
$$

Here, $T$ is a time horizon fulfilling $t \leq T \leq \infty, \rho$ is a discount factor and $\gamma$ is a prechosen probability level.

## 4 Approximation

Denote

$$
h_{\tau}=\mathbb{E}\left(\pi_{\tau} \mid \xi_{\tau}\right), \quad P_{\tau}=\frac{a_{\tau}+b_{\tau}}{2}
$$

the expected (log)fair price, (log)midpoint price, respectievely, and define

$$
\delta_{\tau}=P_{\tau}-h_{\tau}, \quad \sigma_{\tau}=\frac{a_{\tau}-b_{\tau}}{2}
$$

ther relative price, half-spread respectively.
Our next aim is to describe the dyna_mics of $h_{\tau}$ and the distribution of $h_{\tau}^{\prime} s$ observation error

$$
\eta_{\tau}=h_{\tau}-\pi_{\tau}
$$

Because, in cases ( U ) and (P), the dynamics of $h$ comes out as non-linear and the distribution of $\eta_{\tau}$ as non-normal, an approximation is needed. To this end, denote

$$
v_{\eta, \tau}=\operatorname{var}\left(\eta_{\tau} \mid \xi_{\tau}\right)
$$

and observe that, once

$$
r \text { is high enough }
$$

and

$$
\begin{equation*}
a_{t}-h_{t}+\sqrt{v_{\eta, t}}=\sigma_{t}+\delta_{t}+\sqrt{v_{\eta, t}} \ll D, \quad h_{t}-b_{t}+\sqrt{v_{\eta}}=\sigma_{t}-\delta_{t}+\sqrt{v_{\eta, t}} \ll D \tag{4}
\end{equation*}
$$

we may approximate the Compound Poisson conditional distributions of $X_{t}$ and $Y_{t}$ by normal one with first and second moments matching. From the Chebyshev inequality and from (4), we further get that the probability of $a_{t}-h_{t}+\eta_{t}>D, h_{t}-b_{t}-\eta_{t}>D$ is very small (similarly $b_{t}$ ) so we may take $\lambda$ as linear. Therefore, we keep assuming (I1) and (I2) but we approximate
(A1) $X_{t} \left\lvert\, \Xi_{t-1} \dot{\sim} \mathcal{N}\left(R\left(1-\frac{a_{t-1}-\pi_{t-1}}{D}\right), \frac{s}{\mu} R\left(1-\frac{a_{t-1}-\pi_{t-1}}{D}\right)\right)\right.$
(A2) $Y_{t} \mid \Xi_{t-1}, \dot{\sim} \mathcal{N}\left(R\left(1-\frac{\pi_{t-1}-b_{t-1}}{D}\right), \frac{s}{\mu} R\left(1-\frac{\pi_{t-1}-b_{t-1}}{D}\right)\right)$
Further, for each $t$, we assume

$$
\begin{aligned}
\Delta \pi_{t} & \sim \mathcal{N}\left(0, v_{\pi}\right) \\
\zeta_{t} & \sim \mathcal{N}\left(0, v_{\zeta}\right)
\end{aligned}
$$

Unfortunatelly, even given this approximation, we would not get analytical formulas for the conditional distribution of $\eta_{t}$ given $\xi_{t}$ which we will need to describe the dynamics of the price-volume process (the reason being the conditional variance of both $X_{t}$ and $Y_{t}$ dependent on $\eta_{t}$ ). One way to overcome this is to approximate its conditional density; however, since the formulas, resulting from that approach, would still be quite complex hence difficult to work with further, we rather assume that, instead of both the values $X_{t}$ and $Y_{t}$, the MM takes into account only the value the increase of the inventory

$$
\Delta N_{t}=Y_{t}-X_{t}
$$

whose conditional variance does not depend on $\eta_{t}$. This approximation could be justified by the fact that the loss of information given such a simplification is not large. ${ }^{2}$ Hence, we assume
(A3) $\xi_{t}=\left(e_{1}, \Delta N_{1}, \ldots, e_{t}, \Delta N_{t}\right)$
until the end of the paper.
Proposition 2. Given (I1),(I2),(A1)-(A3) and if

$$
\eta_{t-1} \mid \xi_{t-1} \sim \mathcal{N}\left(0, v_{\eta, t-1}\right)
$$

then

$$
\Delta h_{t}=-c_{N}\left(k^{-1} \Delta N_{t}-\delta_{t-1}\right)+c_{e}\left(e_{t}-h_{t-1}\right)
$$

where

$$
\begin{gathered}
k=2 \frac{R}{D} \\
c_{N}=c_{N}\left(v_{\eta, t-1}, \sigma_{t-1}\right)=\frac{v_{\eta, t-1} v_{\zeta}}{u_{t}} \\
c_{e}=c_{e}\left(v_{\eta, t-1}, \sigma_{t-1}\right)=\frac{v_{\eta, t-1} v_{\theta, t}+v_{\pi} v_{\theta, t}+v_{\eta, t-1} v_{\pi}}{u_{t}} \\
u_{t}=u\left(v_{\eta, t-1}, \sigma_{t-1}\right)=v_{\eta, t-1} v_{\pi}+v_{\eta, t-1} v_{\theta, t}+v_{\pi} v_{\theta, t}+v_{\eta, t-1} v_{\zeta}+v_{\theta, t} v_{\zeta} \\
v_{\theta, t}=v_{\theta}\left(\sigma_{t-1}\right)=\frac{s}{k \mu}\left(D-2 \sigma_{t-1}\right)
\end{gathered}
$$

and

$$
\eta_{t} \mid \xi_{t} \sim \mathcal{N}\left(0, v_{\eta, t}\right)
$$

where

$$
\begin{aligned}
v_{\eta, t}=v_{\eta}\left(v_{\eta, t-1}, \sigma_{t-1}\right) & \\
=v_{\eta, t-1}+v_{\pi}-\frac{1}{u_{t}}\left(v_{\eta, t-1}^{2} v_{\zeta}\right. & +v_{\eta, t-1}^{2} v_{\theta, t}+v_{\eta, t-1} v_{\pi} v_{\theta, t} \\
& \left.+v_{\eta, t-1}^{2} v_{\pi}+v_{\eta, t-1} v_{\theta, t} v_{\pi}+v_{\pi}^{2} v_{\theta, t}+v_{\eta, t-1} v_{\pi}^{2}\right)
\end{aligned}
$$

[^1]Proof. Denote

$$
\vartheta_{t}=\frac{\Delta N_{t}}{k}-\delta_{t-1}-\eta_{t-1}
$$

Given (P), we have

$$
\begin{aligned}
& \vartheta_{t}\left|\Xi_{t-1}, \zeta_{t}, \Delta \pi_{t}=\vartheta_{t}\right| \Xi_{t-1} \\
& \dot{\sim} \frac{\mathcal{N}\left(R\left[\left(1-\frac{\pi_{t-1}-b_{t-1}}{D}\right)-\left(1-\frac{a_{t-1}-\pi_{t-1}}{D}\right)\right], \frac{s}{\mu} R\left[\left(1-\frac{a_{t-1}-\pi_{t-1}}{D}\right)+\left(1-\frac{\left.\left.\left.\pi_{t-1-b_{t-1}}^{D}\right)\right]\right)}{k}\right.\right.\right.}{x}-\delta_{t-1}-\eta_{t-1} \\
& =\frac{\mathcal{N}\left(R\left(-\frac{2 \pi_{t-1}-\left(b_{t-1}+a_{t-1}\right)}{D}\right), \frac{s}{\mu} R\left(2-\frac{a_{t-1}-b_{t-1}}{D}\right)\right)}{k}-\delta_{t-1}-\eta_{t-1} \\
& \left.\quad=\frac{\mathcal{N}\left(k\left(\eta_{t-1}+\delta_{t-1}\right), k \frac{s}{\mu}\left(D-2 \sigma_{t-1}\right)\right)}{k}-\delta_{t-1}-\eta_{t-1}=\mathcal{N}\left(0, v_{\theta, t}\right) \sim \vartheta_{t} \right\rvert\, \sigma_{t-1} \\
& v_{\theta, t}=\frac{s}{k \mu}\left(D-2 \sigma_{t-1}\right)
\end{aligned}
$$

(the last " $\sim$ " follows from the fact that the the parameters of the conditional distribution of $\vartheta_{t} \mid \Xi_{t-1}$ are measurable with respect to $\sigma\left(\sigma_{t-1}\right)$ ) from which and the assumptions it is clear that

$$
\vartheta_{t}, \zeta_{t}, \Delta \pi_{t}, \eta_{t-1} \mid \Xi_{t-1} \sim \mathbb{N}\left(0, \operatorname{diag}\left(v_{\vartheta, t}, v_{\zeta, t}, v_{\pi, t}, v_{\eta, t-1}\right)\right)
$$

Now, denote $z_{t}=k^{-1} \Delta N_{t}$. Since

$$
\begin{gathered}
\pi_{t}=h_{t-1}-\eta_{t-1}+\Delta \pi_{t} \\
z_{t}=\delta_{t-1}+\eta_{t-1}+\vartheta_{t}
\end{gathered}
$$

$$
e_{t}=\pi_{t}+\zeta_{t}=h_{t-1}-\eta_{t-1}+\Delta \pi_{t}+\zeta_{t}
$$

we are geting that $\left(\pi_{t}, z_{t}, e_{t}\right)$ given $\xi_{t-1}$ is normal with mean $\left(h_{t-1}, \delta_{t-1}, h_{t-1}\right)$ and variance

$$
\left(\begin{array}{ccc}
v_{\eta, t-1}+v_{\pi} & -v_{\eta, t-1} & v_{\eta, t-1}+v_{\pi} \\
-v_{\eta, t-1} & v_{\theta, t}+v_{\eta, t-1} & -v_{\eta, t-1} \\
v_{\eta, t-1}+v_{\pi} & -v_{\eta, t-1} & v_{\pi}+v_{\zeta}+v_{\eta, t-1}
\end{array}\right)
$$

so, by textbook formula,

$$
\pi_{t} \mid z_{t}, e_{t}, \xi_{t-1}
$$

is normal with mean

$$
\begin{aligned}
h_{t-1}+\left(-v_{\eta, t-1}, v_{\eta, t-1}+v_{\pi}\right) & \left(\begin{array}{cc}
v_{\theta, t}+v_{\eta, t-1} & -v_{\eta, t-1} \\
-v_{\eta, t-1} & v_{\pi}+v_{\zeta}+v_{\eta, t-1}
\end{array}\right)^{-1}\left[\begin{array}{c}
z_{t}-\delta_{t-1} \\
\hat{e}_{t}
\end{array}\right] \\
=h_{t-1}+\frac{1}{u_{t}}\left(-v_{\eta, t-1},\right. & \left.v_{\eta, t-1}+v_{\pi}\right)\left(\begin{array}{cc}
v_{\pi}+v_{\zeta}+v_{\eta, t-1} & v_{\eta, t-1} \\
v_{\eta, t-1} & v_{\theta, t}+v_{\eta, t-1}
\end{array}\right)\left[\begin{array}{c}
z_{t}-\delta_{t-1} \\
e_{t}-h_{t-1}
\end{array}\right] \\
& =h_{t-1}+\frac{1}{u_{t}}\left[-v_{\eta, t-1}\left(v_{\pi}+v_{\zeta}+v_{\eta, t-1}\right)\right. \\
+v_{\eta, t-1}\left(v_{\eta, t-1}+\right. & \left.\left.v_{\pi}\right),-v_{\eta, t-1}^{2}+\left(v_{\eta, t-1}+v_{\pi}\right)\left(v_{\theta, t}+v_{\eta, t-1}\right)\right]\left[\begin{array}{c}
z_{t}-\delta_{t-1} \\
e_{t}-h_{t-1}
\end{array}\right] \\
= & h_{t-1}+\frac{1}{u_{t}}\left(-v_{\eta, t-1} v_{\zeta}, v_{\eta, t-1} v_{\theta, t}+v_{\pi} v_{\theta, t}+v_{\eta, t-1} v_{\pi}\right)\left[\begin{array}{c}
z_{t}-\delta_{t-1} \\
e_{t}-h_{t-1}
\end{array}\right]
\end{aligned}
$$

and variance

$$
\begin{aligned}
v_{\eta, t}= & v_{\eta, t-1}+v_{\pi} \\
& -\frac{1}{u_{t}}\left(v_{\eta, t-1}^{2} v_{\zeta}+v_{\eta, t-1}^{2} v_{\theta, t}+v_{\eta, t-1} v_{\pi} v_{\theta, t}+v_{\eta, t-1}^{2} v_{\pi}+v_{\eta, t-1} v_{\theta, t} v_{\pi}+v_{\pi}^{2} v_{\theta, t}+v_{\eta, t-1} v_{\pi}^{2}\right)
\end{aligned}
$$

Untill the end of the paper assume the case (P), i.e., that the mm is partially informed.

## 5 The optimal decision

Before proceeding, note that, as $h_{\tau}$ is (by definition) $\xi_{\tau}$-measurable, any strategy of (3) may be alternatively expressed by $\left(\delta_{\tau}, \sigma_{\tau}, C_{\tau}\right)$.

The following Proposition shows how the optimal dicesion depends on the past of the MM's information.

Proposition 3. Denote $\left(\delta_{\tau}, \sigma_{\tau}, C_{\tau}\right)_{\tau \geq t}$, be optimal solution of (3). Then,
(i) if

- $T$ is finite
or
- $T=\infty$ and additional constraints

$$
\delta_{\tau} \in\left[-D_{0}, D_{0}\right], \quad \sigma_{\tau} \leq S_{0}, \quad C(\tau)
$$

are added to the problem,
then

- $V_{t}\left(\xi_{t}\right)=V\left(M_{t}, N_{t}, v_{\eta, t}, h_{t}, T-t\right)$ for some function $V$
- $\delta_{\tau}=\delta\left(N_{\tau}, v_{\eta, \tau}, T-\tau\right), \sigma_{t}=\sigma\left(N_{\tau}, v_{\eta, \tau}, T-\tau\right)$ for some functions $\delta, \sigma$
- $C_{\tau}=C\left(M_{t}, N_{\tau}, v_{\eta, \tau}, h_{\tau}\right)$ for some function $C$.
(ii) For $T=\infty$ and given constraint $\mathcal{C}$,

$$
V(M, N, v, h)=\frac{1}{1-e^{-\rho}} M_{\tau}+e^{h_{\tau}} W(N, v)
$$

where $W$ is given by a "Bellman-like" equation

$$
\begin{aligned}
& W(n, v)=\sup _{\delta, \sigma}\left\{\phi(\delta, \sigma)+\frac{1}{e^{\rho}-1} R\left[e^{\delta+\sigma}\left(1-\frac{\delta+\sigma}{D}\right)-e^{\delta-\sigma}\left(\frac{\delta-\sigma}{D}-1\right)\right]\right. \\
& \left.+\mathbb{E}\left[e^{w(\delta, \sigma, \Delta N)} W\left(n+\Delta N, v_{\eta}(v, \sigma)\right)\right]\right\} \\
& \text { s.t. } \\
& \delta \in\left[-D_{0}, D_{0}\right], \\
& \sigma \in\left[0, S_{0}\right] \\
& \mathbb{P}(\Delta N+N<0) \leq \gamma
\end{aligned}
$$

Here,

- $\Delta N \sim \mathcal{N}\left(k \delta, k^{2}\left(v+v_{\theta}(v, \sigma)\right)\right)$
- $k, R, \rho, D, \gamma, D_{0}, S_{0}$ are previously defined constants
- $c_{N}, c_{e}, v_{\eta}, v_{\theta}$ are previously defined functions
- $\phi(\sigma, \delta)=\sup \{x ; \Psi(x ; \delta, \sigma) \leq \gamma\}$,

$$
\Psi(z ; \delta, \sigma)=\mathbb{E}_{\eta \sim \mathcal{N}(0, v)} \varphi\left(\frac{e^{-\delta} z-e^{\sigma} R(D-(\sigma+\delta+\eta))-e^{-\sigma}(D-(\sigma-\delta-\eta))}{\sqrt{\frac{R s}{\mu}}\left[e^{2 \sigma}(D-(\sigma+\delta+\eta))+e^{-2 \sigma}(D-(\sigma-\delta-\eta))\right]}\right)
$$

- $w(\delta, \sigma, \Delta N)=\frac{c_{e}(v, \sigma)}{v+v_{\theta}(v, \sigma)}\left(k^{-1} \Delta N-\delta\right)+\frac{1}{2} c_{e}(v, \sigma)^{2}\left(v+v_{\pi}+v_{\zeta}-\frac{k^{2} v^{2}}{v+v_{\theta}(v, \sigma)}\right)-c_{N}(v, \sigma) \Delta N$
(iii) $V_{t}$ is non-decreasing both in $M_{t}$ and $N_{t}$
(iv) The constraint $\mathcal{M}(\tau)$ is fulfilled with " $=$ " for all $\tau \geq t$

Proof. (i): Assume first that $T<\infty$. Then the problem (3) may be reformulated by means of Bellman equations

$$
V\left(\xi_{\tau}\right) \quad=\quad \sup _{\delta_{\tau}, \sigma_{\tau}, C_{\tau} \text { fulfilling } \mathcal{A}(\tau), \mathcal{M}(\tau), \mathcal{N}(\tau)}\left[C_{\tau}+e^{-\rho} \mathbb{E}\left(V_{\tau+1}\left(\xi_{\tau+1}\right) \mid \xi_{\tau}\right)\right]
$$

for $t \leq \tau<T$ and

$$
V_{T}\left(\xi_{T}\right)=\mathbb{E}\left(M_{T}+e^{\pi_{T}} N_{T} \mid \xi_{T}\right)=M_{T}+\mathbb{E}\left(e^{\pi_{T}} \mid \xi_{T}\right) N_{T}
$$

We prove, by induction, that, for all $t \leq \theta \leq T$,

$$
\begin{equation*}
V_{\theta}\left(\xi_{\theta}\right)=\tilde{V}\left(M_{\theta}, N_{\theta}, h_{\theta}, v_{\eta, \theta}, T-\theta\right)=d_{T-\theta} M_{\theta}+e^{h_{\theta}} W\left(N_{\theta}, v_{\eta, \theta}, T-\theta\right) \tag{5}
\end{equation*}
$$

for some functions $\tilde{V}$ and $W$ such that $W$ is non-decreasing in $N$ and $d_{\theta} \in \mathbb{R}$ is deterministic.
If $\theta=T$ then (5) clearly holds with $d_{0}=1$ and

$$
W(n, v, 0)=n \mathbb{E}_{\eta \sim \mathcal{N}(0, v)} e^{-\eta}=n e^{v^{2} / 2}
$$

(to see it, note that $\left.\mathbb{E}\left(e^{\pi_{T}} \mid \xi_{T}\right)=\mathbb{E}\left(e^{-\eta_{T}} e^{h_{T}} \mid \xi_{T}\right)=e^{h_{T}} \mathbb{E}\left(e^{-\eta_{T}} \mid \xi_{T}\right)\right)$
Now let $\tau<T$ and assume (5) to hold with $\theta=\tau+1$. Put

$$
x_{\tau}=e^{-h_{\tau}}\left(C_{\tau}-M_{\tau}\right)
$$

Since

$$
\Delta M_{\tau+1}=e^{h_{\tau}}\left(e^{\delta_{\tau}+\sigma_{\tau}} X_{\tau+1}-e^{\delta_{\tau}-\sigma_{\tau}} Y_{\tau+1}\right)
$$

we are getting

$$
\begin{aligned}
& V_{\tau}\left(\xi_{t}\right)=\sup _{\delta_{\tau}, \sigma_{\tau}, x_{\tau} \text { fulfiling } \mathcal{A}(\tau), \mathcal{M}(\tau), \mathcal{N}(\tau)} \\
& \begin{array}{r}
{\left[M_{\tau}+e^{h_{\tau}} x_{\tau}+e^{-\rho} \mathbb{E}\left(d_{T-(\tau+1)} M_{\tau+1}+e^{h_{\tau+1}} W\left(N_{\tau+1}, v_{\eta, \tau+1}, T-(\tau+1)\right)\right)\right]} \\
\quad=\left(1+e^{-\rho} d_{T-(\tau+1)}\right) M_{\tau} \\
+e^{h_{\tau}} \sup _{\delta_{t}, \sigma_{t}, x_{t}, \ldots}\left[x_{\tau}+e^{-\rho} d_{T-(\tau+1)} e^{-h_{\tau}} \mathbb{E}\left(\Delta M_{\tau+1} \mid \xi_{\tau}\right)\right. \\
\left.+\mathbb{E}\left(e^{\Delta h_{\tau+1}} W\left(N_{\tau+1}, v_{\eta, \tau+1}, T-(\tau+1)\right) \mid \xi_{\tau}\right)\right] \\
\\
\quad=\left(1+e^{-\rho} d_{T-(\tau+1)}\right) M_{\tau}+e^{h_{\tau}} F\left(N_{\tau}, v_{\eta, \tau+1}, T-\tau\right)
\end{array}
\end{aligned}
$$

where

$$
\begin{align*}
F(N, v, \theta)=\sup _{\delta, \sigma}\left\{\phi(\delta, \sigma)+e^{-\rho} d_{\theta-1} R\right. & {\left[e^{\delta+\sigma}\left(1-\frac{\delta+\sigma}{D}\right)-e^{\delta-\sigma}\left(\frac{\delta-\sigma}{D}-1\right)\right) } \\
& \left.+\mathbb{E}\left(e^{-c_{N}(v, \sigma) \Delta N+c_{e}(v, \sigma) e} W\left(N+\Delta N, v_{\eta}(v, \sigma), \theta-1\right)\right)\right] \tag{6}
\end{align*}
$$

s.t.

$$
\begin{equation*}
\sigma \geq 0 \tag{A}
\end{equation*}
$$

$$
\begin{equation*}
\mathbb{P}(\Delta N+N<0) \leq \gamma \tag{N}
\end{equation*}
$$

where

$$
\left[\begin{array}{c}
\Delta N \\
e
\end{array}\right] \sim \mathcal{N}\left(\left[\begin{array}{c}
k \delta \\
0
\end{array}\right],\left[\begin{array}{cc}
k^{2}\left(v+v_{\theta}(v, \sigma)\right) & -k v \\
-k v & v+v_{\pi}+v_{\zeta}
\end{array}\right]\right)
$$

Finally, since, by a textbook formula,

$$
e \left\lvert\, \Delta N \sim \mathcal{N}\left(-\frac{v}{v+v_{\theta}(v, \sigma)}\left(k^{-1} \Delta N_{t}-\delta_{t-1}\right), v+v_{\pi}+v_{\zeta}-\frac{k^{2} v^{2}}{v+v_{\theta}(v, \sigma)}\right)\right.
$$

we have

$$
\begin{aligned}
& \mathbb{E}\left(e^{-c_{N}(v, \sigma) \Delta N+c_{e}(v, \sigma) e} W\right)=\mathbb{E}\left(\mathbb{E}\left(e^{-c_{N}(v, \sigma) \Delta N+c_{e}(v, \sigma) e} W \mid \Delta N\right)\right) \\
& \quad=\mathbb{E}\left(\mathbb{E}\left(e^{c_{e}(v, \sigma) e} \mid \Delta N\right) e^{-c_{N}(v, \sigma) \Delta N} W\right)=\mathbb{E}\left(e^{w(\delta, \sigma, \Delta N)} W\right)
\end{aligned}
$$

so

$$
\begin{aligned}
& F(N, v, \theta)=\sup _{\delta, \sigma}\left\{\phi(\delta, \sigma)+e^{-\rho} d_{\theta-1} R\left[e^{\delta+\sigma}\left(1-\frac{\delta+\sigma}{D}\right)-e^{\delta-\sigma}\left(\frac{\delta-\sigma}{D}-1\right)\right)\right. \\
&\left.+\mathbb{E}\left(e^{w(\sigma, \delta, \Delta N)} W\left(N+\Delta N, v_{\eta}(v, \sigma), \theta-1\right)\right)\right]
\end{aligned}
$$

Therefore, $V_{\tau}\left(\xi_{\tau}\right)$ and the optimal solutions depend, in fact, only on $N_{\tau}, M_{\tau}, h_{\tau}, v_{\eta, \tau}, T-\tau$ and, specially, $\delta_{\tau}, \sigma_{\tau}$ depends only on $N_{\tau}, v_{\eta, t}, T-\tau$.

As to the monotony: since $W$ is non-decreasing in $N$ and neigther $v$ nor $(X, Y, e)$ depend on $N$, we are getting that, given the same strategy, the value of (6) is greater given a greater $N$. Finally, as any strategy feasible given less $N$ is feasible given any greater $N$, the monotony is proved.

Now, let $T=\infty$. We have

$$
\begin{aligned}
& V\left(\xi_{t}\right)=\sup _{\delta_{\tau}, \sigma_{\tau}, C_{\tau}, \text { fulfilling } \mathcal{C}(\tau), \mathcal{A}(\tau), \mathcal{M}(\tau), \mathcal{N}(\tau), \tau \geq t} \mathbb{E}\left[\lim _{T \rightarrow \infty} \sum_{\tau=t}^{T} e^{-\rho(\tau-t)} C_{\tau} \mid \xi_{t}\right] \\
& \left.=\sup _{\substack{\delta_{\tau}, \sigma_{\tau} \text { fulfiling } \mathcal{C}(\tau), \mathcal{A}(\tau), \mathcal{N}(\tau) \\
p_{\tau} \in[0,1], \varphi^{-1}\left(p_{\tau}\right) \leq\left(e^{h} \tau \phi\left(\delta \tau, \tau_{\tau}\right)+M_{\tau}\right), \tau \geq t}} \mathbb{E}\left[\lim _{T \rightarrow \infty} \sum_{\tau=t}^{T} e^{-\rho(\tau-t)} \varphi^{-1}\left(p_{\tau}\right)\right) \mid \xi_{t}\right]
\end{aligned}
$$

$$
\begin{align*}
& =\lim _{T \rightarrow \infty} \sup _{\delta_{\tau}, \sigma_{\tau}, C_{\tau}, \text { fulfilling } \mathcal{A}(\tau), \mathcal{M}(\tau), \mathcal{N}(\tau), T \geq \tau \geq t} \mathbb{E}\left[\sum_{\tau=t}^{T} e^{-\rho(\tau-t)} C_{\tau} \mid \xi_{t}\right] \\
& =\lim _{T \rightarrow \infty} \tilde{V}\left(M_{\tau}, N_{\tau}, h_{\tau}, v_{\eta, \theta}, T-t\right) \\
& =\lim _{T \rightarrow \infty} \sup _{\delta_{t}, \sigma_{t}, C_{t}, \text { fulfilling } \mathcal{A}(t), \mathcal{M}(t), \mathcal{N}(t)}\left[C_{t}+e^{-\rho} \mathbb{E}\left(\tilde{V}\left(M_{\tau}, N_{\tau}, h_{\tau}, v_{\eta, \theta}, T-(t+1)\right) \mid \xi_{\tau}\right)\right] \\
& =\sup _{\delta_{t}, \sigma_{t}, C_{t}, \text { fulfilling } \mathcal{A}(t), \mathcal{M}(t), \mathcal{N}(t)}\left[C_{t}+e^{-\rho} \mathbb{E}\left(\lim _{T \rightarrow \infty} \tilde{V}\left(M_{\tau}, N_{\tau}, h_{\tau}, v_{\eta, \theta}, T-(t+1)\right) \mid \xi_{\tau}\right)\right] \\
& =\sup _{\delta_{t}, \sigma_{t}, C_{t}, \text { fulfilling } \mathcal{A}(t), \mathcal{M}(t), \mathcal{N}(t)}\left[C_{\tau}+e^{-\rho} \mathbb{E}\left(V\left(\xi_{\tau+1}\right) \mid \xi_{\tau}\right)\right] \tag{7}
\end{align*}
$$

The third equality follows from Fatou-Lesbeque theorem (allowing to change the order of limit and expectation) and variational analysis theory. Since $\varphi^{-1}\left(p_{\tau}\right)$ is a monotone and differentiable function for all $\tau$ almost surely, the objective functions: $f_{T}=\mathbb{E}\left(\sum_{\tau=t}^{T} \varphi^{-1}\left(p_{\tau}\right) \mid \xi_{t}\right)$ are monotone and differentiable, too. Moreover, the feasible solutions of the problem form a compact set. Monotonicity, differentiability and compactness imply the epi-convergence of $f_{T}$ to $f_{\infty}=\mathbb{E}\left(\sum_{\tau=t}^{\infty} \varphi^{-1}\left(p_{\tau}\right) \mid \xi_{t}\right)$. Finally, having compact set of feasible solutions, the epi-convergence of objectives functions allows for interchange of supremum and limit. See [1](Theorem 1.10, Theorem 2.11) or [3](Th. 7.33) for more details.

It is clear from the third " $=$ " of (7) that $V\left(\xi_{t}\right)$ depends only on $h_{t}, M_{t}, N_{t}, v_{\eta, t}, T-t$ and, as $\lim _{T} f(T-t)$ never depends on $t$ whatever $f$ is, it is clear that in fact $V\left(\xi_{t}, \infty\right)$ does not depend on $t$. The properties of $a$ and $b$ may be proved analogously to the case of finite horizon, using the equality of the first and last term in (7). The monotony of $V$ follows from the fact that a limit of monotonous functions is monotonous.
(ii) Follows from the previous.
(iii) The monotony in $N$ follows from the monotony of $W$, the monotony in $M$ from (5).
(iv) Follows from the facts that the function on the LHS of constraint ( $\tilde{\mathcal{M}}$ ) of problem (6) is non-decreasing in $x$ and that the constraint $(\tilde{\mathcal{N}})$ does not depend on $x$.

## 6 The Price and Volume

As it was already written above, our goal is to determine the joint dynamics of the midpoint price $P_{t}$ and the the MM's inventory $N_{t}$. If we approximate

$$
\delta(n, v) \doteq d_{0}+d_{1} n+d_{2} v
$$

we get that, up to a constant, the price may be decomposed as follows

$$
P_{\tau}=\underbrace{\pi_{\tau}}_{\text {fair price }}+\underbrace{\eta_{\tau}+d_{2} v_{\eta, \tau-1}}_{\text {uncertainty }}+\underbrace{d_{1} N_{\tau}}_{\text {inventory }}
$$

which is analogous to a well known decomposition of spread, widely discussed in market macrostructure. If we further linearize

$$
\sigma(n, v)=s_{0}+s_{1} n+s_{2} v, \quad v_{\eta}(v, \sigma)=w_{0}+w_{1} \sigma+w_{2} v
$$

we get

$$
v_{\eta, \tau}=w_{0}+w_{1} \sigma_{\tau-1}+w_{2} v_{\eta, \tau-1}=w_{0}+w_{1} \sigma_{\tau-1}-\frac{w_{2}}{s_{2}}\left(s_{0}+s_{1} N_{\tau-1}\right)
$$

and, consequently,

$$
\begin{aligned}
\delta\left(N_{\tau}, v_{\eta, \tau}\right) \doteq d_{0}+d_{1} N_{\tau}+d_{2}\left(w_{0}+w_{1} \sigma_{\tau-1}-\frac{w_{2}}{s_{2}}\left(s_{0}+\right.\right. & \left.\left.s_{1} N_{\tau-1}\right)\right) \\
& =\beta_{0}+\beta_{\sigma} \sigma_{\tau-1}+\beta_{\Delta N} \Delta N_{\tau}+\beta_{N} N_{\tau-1}
\end{aligned}
$$

If we futher linearly approximate $c_{N}(v, \sigma) \equiv c_{N}$ and $c_{e}(v, \sigma) \equiv c_{e}$, we get

$$
\begin{aligned}
\Delta P_{\tau}= & \Delta h_{\tau}+\Delta \delta\left(N_{\tau}, v_{\eta, \tau}\right)=c_{N}\left(k^{-1} \Delta N_{\tau}-\delta\left(N_{\tau}, v_{\eta, \tau}\right)\right)+c_{e}\left(e_{t}-h_{t-1}\right)+\Delta \delta\left(N_{\tau}, v_{\eta, \tau}\right) \\
& \doteq \phi_{0}+\phi_{\Delta \sigma} \Delta \sigma_{\tau-1}+\phi_{\sigma} \sigma_{\tau-2}+\phi_{\Delta N} \Delta N_{\tau}+\phi_{\Delta N_{-1}} \Delta N_{\tau-1}+\phi_{N} N_{\tau-2}+E_{\tau}
\end{aligned}
$$

where $E_{\tau}$ are i.i.d. The following shows results of estimation of the latter equation based on 51412 observations of 10 -second snapshots data of Exxon Mobile on ISE narket.


## 7 Alternative models

Finally, let us discuss two alternative (sub) models and show that they are rejected in favour of our model.

### 7.1 Irrational liquidity takers

Assume, in the present Subsection, that the liquidity takers do not consider (their estimate of) the fair price but they buy and sell the stocks randomly, i.e.

$$
X_{\tau}\left|\Xi_{\tau-1} \sim \mathrm{CP}(\lambda), \quad Y_{\tau}\right| \Xi_{\tau-1} \sim \mathrm{CP}(\lambda)
$$

This, however, means that $X_{\tau}, Y_{\tau}$, hence $\Delta N_{\tau}$, are independent of all the past, namely of $\Delta N_{\tau-1}$. This is, however, not true, as the correlation coeffitient of $\Delta N_{\tau}$ and $\Delta M_{\tau-1}$, compoted from the data above, is significant on 0.0000 probability level.

### 7.2 Irrational market makers

Another possible violation of our model could be that the MM's do not (cannot) act rationally but they "take prices as they come". In particular, that once a market order arrives and causes a movement of its corresponding quote, the MM sets the new quote so that its jump (w.r.t. its value before the market order arrival) is proportional to the impact of the market order, which could be mathematically expressed as

$$
\Delta M_{\tau}=\beta \Delta N_{\tau}+\epsilon_{\tau}
$$

Hosever, even this model is convincingly rejected by adding $\Delta M_{\tau-1}$ into the regression and observing that the probability level of the corresponding regressor is 0.0000 .

## 8 Conclusion

A model of a rational behaviour of a risk averse partially informed market maker solving multistage decision problem was proposed, implying an easily tractable and estimable stochastic model of high frequency trade and quote data process, which was subsequently successfully tested by means of data from US electronic markets.

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[^0]:    ${ }^{1}$ Other trading frequencies may be modelled by scaling of the time.

[^1]:    ${ }^{2}$ As, due to (4), the variances of $Y_{t}$ and $X_{t}$ are similar and their relation to $e_{t}$ is analogous, their contribution to the information about $\pi_{t}$ is similar too so the same absolute value of coeffitients in an eventual linear estimate of $\pi_{t}$ are defensitble; moreover, as they depend on $\pi_{t}$ reverse way, the signs of the coeffitient should clearly be opposite.

