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On Computation of Generalized Derivatives of the Normal-Cone Mapping and Their Applications

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The paper concerns the computation of the graphical derivative and the regular (Fréchet) coderivative of the normal-cone mapping related to C^2 inequality constraints under very weak qualification conditions. This enables us to provide the graphical derivative and the regular coderivative of the solution map to a class of parameterized generalized equations with the constraint set of the investigated type. On the basis of these results, we finally obtain a characterization of the isolated calmness property of the mentioned solution map and derive strong stationarity conditions for an MPEC with control constraints.

Keywords: parameterized generalized equation; graphical derivative; regular coderivative; mathematical program with equilibrium constraints

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1. Introduction. Various generalized derivatives introduced in modern variational analysis represent an efficient tool in stability analysis of multifunctions (Rockafellar and Wets [26], Klatte and Kummer [13], Borwein and Zhu [3], Mordukhovich [16], Dontchev and Rockafellar [5]). This concerns in particular the so-called solution maps associated with parameter-dependent variational inequalities or generalized equations. Their stability properties have been thoroughly analyzed already in the seventies, above all in the papers by Robinson. A particular attention has been paid to the case of polyhedral constraint sets, independent of the parameter; see, for instance, Robinson [21, 22, 24] and Dontchev and Rockafellar [4]. An overview of available results in this situation can be found in Dontchev and Rockafellar [5, Chapter 2E]. Concerning nonpolyhedral constraint sets, one can find a huge number of works related to constraint sets with nonlinear programming structure, possibly even parameter dependent. They deal with various types of stability, including the strong regularity of Robinson [23] and various other types of "regular" behavior; see Klatte and Kummer [13] and the references therein.

Another group of results concerns the so-called conic constraints; cf. Bonnans and Shapiro [2]. They are formulated either in the general framework or for special important classes of cones (SDP cones, Lorentz cones, etc.).

In the first part of the present paper our main attention is paid to the graphical derivative and the regular coderivative of the normal-cone mapping

$$y \mapsto \hat{N}_{\Gamma}(y),$$
 (1)

where

$$\Gamma = \{ y \in \mathbb{R}^m \mid q_i(y) \le 0, \ i = 1, 2, \dots, l \}$$
(2)

with twice continuously differentiable functions $q_i: \mathbb{R}^m \to \mathbb{R}$. In (1), \hat{N}_{Γ} stands for the regular normal cone to Γ defined at the beginning of the Section 2. The graphical derivative of (1) has been computed in Rockafellar and Wets [26, Corollary 13.43(a), Exercise 13.17] in the case when Γ is a fully amenable set (i.e., locally, the preimage of a polyhedral set under a constraint qualification). In the case of Γ given by (2) and $\bar{y}^* \in \hat{N}_{\Gamma}(\bar{y})$, this formula attains the form

$$D\hat{N}_{\Gamma}(\bar{y}, \bar{y}^*)(v) = \{\nabla^2(\lambda^T q)(\bar{y})v \mid \lambda \in \Lambda(v)\} + N_{K(\bar{y}, \bar{y}^*)}(v), \quad v \in \mathbb{R}^m,$$
(3)

where $q(\cdot) = (q_1(\cdot), ..., q_m(\cdot))^T$,

$$\bar{\Lambda}(v) = \underset{\substack{\nabla q(\bar{y})^T \lambda = \bar{y}^* \\ \lambda \in N_{\mathbb{R}^L}(q(\bar{y}))}}{\arg m_{\lambda \in N_{\mathbb{R}^L}(q(\bar{y}))}} \langle v, \nabla^2 (\lambda^T q) (\bar{y}) v \rangle$$

and

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$$K(\bar{y}, \bar{y}^*) := T_{\Gamma}(\bar{y}) \cap \{\bar{y}^*\}^{\perp}$$

is the critical cone to Γ at \bar{y} with respect to \bar{y}^* . Formula (3) can be viewed as a starting point of two lines of research directed to the relaxation of the full amenability of Γ assumed in Rockafellar and Wets [26]. In the first line, one does not require the polyhedrality of Γ in order to be able to deal with the problems of second-order or semidefinite cone programming (Mordukhovich et al. [19]). In the second line, followed in this paper, we will concentrate on Γ given by (2) and relax the constraint qualification associated with amenability, which in this case amounts to the classical Mangasarian-Fromovitz constraint qualification (MFCQ).

Concerning the regular coderivative of \hat{N}_{Γ} for Γ given by (2), it has been studied in Henrion et al. [11] and [10] under MFCQ and the constant rank constraint qualification (CRCQ), which are also substantially more restrictive than the qualification conditions imposed in this paper.

In the next part of the paper, we consider the *solution map S*, which assigns to each value of the *parameter* $x \in \mathbb{R}^n$ the corresponding set of solutions to the (parameterized) generalized equation (GE)

$$0 \in F(x, y) + \tilde{N}_{\Gamma}(y), \tag{4}$$

and a modified solution map \tilde{S} taking into account also possible parameter constraints. In (4), $y \in \mathbb{R}^m$ is the *decision* variable and $F: \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}^m$ is a continuously differentiable mapping. On the basis of the graphical derivative of \hat{N}_{Γ} it is not difficult to compute the graphical derivative of S (or its outer estimate). On the contrary, the computation of the regular coderivative of S (respectively, \tilde{S}) requires apart from the regular coderivative of \hat{N}_{Γ} also the fulfillment of another qualification condition, which is typically rather restrictive. To relax it, we have invoked the idea of *nondegeneracy*, which we have extended from the original convex framework (see Bonnans and Shapiro [2, p. 315]) to a nonconvex one. This technique has enabled us to derive a new calculus rule for the regular normal cone to a "set with constraint structure" (Rockafellar and Wets [26, Theorem 6.14]) and, eventually, to compute the regular coderivative of S (respectively, \tilde{S}).

The last part of the paper is devoted to applications. On the basis of the graphical derivative of S, we state there a new criterion for the isolated calmness of S (at a given point from the graph of S), which is a valuable stability property and may be used, e.g., in postoptimal analysis. Further, on the basis of the regular coderivative of S we have derived sharp necessary optimality conditions for an optimization problem, where (4) arises among the constraints. Such problems are termed mathematical programs with equilibrium constraints (MPECs) and represent a typical application area for new techniques of variational analysis.

The structure of the paper is as follows. In the first of two preparatory sections (Section 2) we provide a background from variational analysis. Apart from standard notions and properties, we introduce in Definition 2 a new stability property for multifunctions, which plays a crucial role in further development. In Section 3, the second preparatory section, we fix the notation and state some simple auxiliary results. The main results are collected in Sections 4 and 5. These sections deal with the two mentioned generalized derivatives of \hat{N}_{Γ} and with the regular coderivatives of S and \tilde{S} , respectively. Section 6 is devoted to applications and, finally, in Section 7 we present concluding remarks on the results obtained.

Our notation is basically standard: conv Ω and ri Ω denote the convex hull and the relative interior of the set Ω , respectively, gph Φ stands for the graph of the map Φ and span $\{a, b\}$ signifies the linear subspace generated by vectors a, b. Furthermore, $\stackrel{\Omega}{\rightarrow}$ denotes convergence within the set Ω , for a cone K its negative polar is denoted by K° , $\|\cdot\|$ stands for the Euclidean norm, and ker A means the kernel of the matrix A. Finally, |I| is the cardinality of the index set I, Ω^{\perp} denotes the orthogonal complement to Ω , $o: \mathbb{R}^+ \to \mathbb{R}$ denotes a function with the property that $o(\lambda)/\lambda \to 0$ when $\lambda \downarrow 0$, and $d(\cdot, \Omega)$ signifies the (Euclidean) distance function to Ω .

2. Background from variational analysis. In this section, we briefly review some generalized differential constructions employed in the paper, confining ourselves only to the settings that appear below. The reader can find more details and extended frameworks in the monographs (Mordukhovich [16], Rockafellar and Wets [26]) and in the papers we refer to.

Let us start with geometric objects. Given a set $\Omega \subset \mathbb{R}^d$ and a point $\overline{z} \in \Omega$, define the (Bouligand-Severi) *tangent/contingent cone* to Ω at \overline{z} by

$$T_{\Omega}(\bar{z}) := \limsup_{t \downarrow 0} \frac{\Omega - \bar{z}}{t} = \left\{ u \in \mathbb{R}^d \mid \exists t_k \downarrow 0, \ u_k \to u \text{ with } \bar{z} + t_k u_k \in \Omega, \ \forall k \right\}.$$
(5)

Note that one has $T_{\Omega}(\bar{z}) = \mathbb{R}_{+}(\Omega - \bar{z})$ when Ω is a convex polyhedron.

The (Fréchet) regular normal cone to Ω at $\overline{z} \in \Omega$ can be equivalently defined by

$$\hat{N}_{\Omega}(\bar{z}) := \left\{ v^* \in \mathbb{R}^d \ \left| \ \limsup_{\substack{z \to \bar{z} \\ z \to \bar{z}}} \frac{\langle v^*, z - \bar{z} \rangle}{\|z - \bar{z}\|} \le 0 \right\} = (T_{\Omega}(\bar{z}))^\circ.$$
(6)

Further, the (Mordukhovich) *limiting/basic normal cone* to Ω at $\overline{z} \in \Omega$ is given by

$$N_{\Omega}(\bar{z}) := \limsup_{z \to \bar{z}} \tilde{N}_{\Omega}(z).$$

The above notation Lim sup stands for the outer set limit in the sense of Painlevé–Kuratowski; see, e.g., Rockafellar and Wets [26, Chapter 4]. Note that the tangent/contingent cone and the regular normal cone reduce to the classical tangent cone and normal cone of convex analysis, respectively, when the set Ω is convex.

Considering next set-valued (in particular, single-valued) mappings Ψ : $\mathbb{R}^d \rightrightarrows \mathbb{R}^s$, we define for them the corresponding derivative and coderivative constructions generated by the tangent cone (5) and the normal cone (6), respectively. Given $(\bar{z}, \bar{w}) \in \text{gph } \Psi$, the graphical derivative $D\Psi(\bar{z}, \bar{w})$: $\mathbb{R}^d \rightrightarrows \mathbb{R}^s$ of Ψ at (\bar{z}, \bar{w}) is

$$D\Psi(\bar{z},\bar{w})(u) := \{ v \in \mathbb{R}^s \mid (u,v) \in T_{\mathrm{gph}\,\Psi}(\bar{z},\bar{w}) \}, \quad u \in \mathbb{R}^d.$$

$$\tag{7}$$

From the dual perspective, we define the *regular coderivative* $\hat{D}^*\Psi(\bar{z},\bar{w})$: $\mathbb{R}^s \rightrightarrows \mathbb{R}^d$ of Ψ at $(\bar{z},\bar{w}) \in \operatorname{gph} \Psi$ generated by the regular normal cone (6) as

$$\hat{D}^*\Psi(\bar{z},\bar{w})(v^*) := \{ u^* \in \mathbb{R}^d \mid (u^*, -v^*) \in \hat{N}_{gph\,\Psi}(\bar{z},\bar{w}) \}, \quad v^* \in \mathbb{R}^s.$$
(8)

If Ψ is single valued at \bar{z} , we drop \bar{w} in the notation of (7)–(8). In the case of smooth single-valued mappings, for all $u \in \mathbb{R}^d$ and $v^* \in \mathbb{R}^s$ we have the representation

$$D\Psi(\overline{z})(u) = \{\nabla\Psi(\overline{z})u\}$$
 and $\hat{D}^*\Psi(\overline{z})(v^*) = \{\nabla\Psi(\overline{z})^Tv^*\}.$

In variational analysis, an important role is played by various stability notions for multifunctions. In the sequel, we will be extensively using the following two:

DEFINITION 1. Let Ψ : $\mathbb{R}^d \rightrightarrows \mathbb{R}^s$ be a multifunction, let $(\bar{u}, \bar{v}) \in \operatorname{gph} \Psi$ and let $\kappa > 0$.

1. Ψ is called *metrically regular with modulus* κ near (\bar{u}, \bar{v}) if there are neighborhoods U of \bar{u} and V of \bar{v} such that

$$d(u, \Psi^{-1}(v)) \le \kappa \, d(v, \Psi(u)), \quad \forall (u, v) \in U \times V.$$
(9)

2. Ψ is called *metrically subregular with modulus* κ at (\bar{u}, \bar{v}) if there is a neighborhood U of \bar{u} such that

$$d(u, \Psi^{-1}(\bar{v})) \le \kappa \, d(\bar{v}, \Psi(u)), \quad \forall u \in U.$$
(10)

It is well known that metric regularity of the multifunction Ψ near (\bar{u}, \bar{v}) is equivalent to the Aubin property (also called Lipschitz-like or pseudo-Lipschitz) of the inverse multifunction Ψ^{-1} and metric subregularity of Ψ at (\bar{u}, \bar{v}) is equivalent with the property of *calmness* of its inverse.

For general multifunctions, the property of metric regularity is characterized by the so-called Mordukhovich criterion; see, e.g., Mordukhovich [15, 16, Theorem 4.18].

In the sequel, we are dealing mostly with the perturbation mapping $M: \mathbb{R}^m \rightrightarrows \mathbb{R}^l$ associated with (2), which is defined by

$$M(y) := q(y) - \mathbb{R}^l_-$$

In this case one can ensure the metric regularity or the metric subregularity via the following statements. The first one follows immediately from Rockafellar and Wets [26, Exercise 9.44].

PROPOSITION 1. Given $\bar{y} \in \Gamma$, *M* is metrically regular near $(\bar{y}, 0)$ if and only if

$$\ker(\nabla q(\bar{y})^T) \cap \hat{N}_{\mathbb{R}^l}(q(\bar{y})) = \{0\}.$$
(11)

The infimum of the moduli κ for which the metric regularity property holds is equal to

$$\max_{\substack{\lambda \in \hat{N}_{\mathbb{R}^{l}}(q(\bar{y})), \\ \|\lambda\|=1}} \frac{1}{\|\nabla q(\bar{y})^{T}\lambda\|}.$$
(12)

It is well known that condition (11) is equivalent to the classical MFCQ at \bar{y} .

For the next statement, we need the notion of the *linearized tangent cone* at some point $y \in \Gamma$ defined by

$$T_{\Gamma}^{\mathrm{lin}}(\mathbf{y}) := \{ v \in \mathbb{R}^m \mid \nabla q_i(\mathbf{y}) v \le 0, \ i \in \mathcal{F}(\mathbf{y}) \},\$$

where $\mathcal{F}(y) := \{i \in \{1, ..., l\} \mid q_i(y) = 0\}$ denotes the index set of constraints, active at y.

PROPOSITION 2 (Second-Order Sufficient Condition for Metric Subregularity GFRERER [6, Theo-REM 6.1]). Let $\bar{y} \in \Gamma$ and assume that for every $0 \neq u \in T_{\Gamma}^{\text{lin}}(\bar{y})$ one has

$$\lambda \in \ker(\nabla q(\bar{y})^T) \cap \hat{N}_{\mathbb{R}^l}(q(\bar{y})), \qquad u^T \nabla^2(\lambda^T q)(\bar{y}) u \ge 0 \implies \lambda = 0.$$

Then M is metrically subregular at $(\bar{y}, 0)$.

We will refer to this condition by using the acronym SOSCMS. In the literature one can find also other sufficient conditions for metric subregularity; see, e.g., Henrion and Outrata [9], Ioffe and Outrata [12], and Zheng and Ng [27, 28].

It can be easily seen from Proposition 1 that metric regularity of M implies SOSCMS.

In some situations M is not metrically regular near $\bar{y} \in \Gamma$ but enjoys a weaker property defined below.

DEFINITION 2. Let $\bar{y} \in \Gamma$, $\kappa > 0$. We say that M is metrically regular (with modulus κ) in the vicinity of \bar{y} , if there is some neighborhood V of \bar{y} such that for every $y \in M^{-1}(0) \cap V$, $y \neq \bar{y}$, the multifunction M is metrically regular near (y, 0) with modulus κ .

Since metric regularity is an open property in the sense that it holds in a neighborhood of the point in question, we easily conclude that metric regularity near $(\bar{y}, 0)$ implies metric regularity in the vicinity of \bar{y} .

The following proposition states that by SOSCMS we have an easily applicable criterion for verifying metric regularity in the vicinity of \bar{y} at hand, when MFCQ does not hold.

PROPOSITION 3. Let $\bar{y} \in \Gamma$. Under SOSCMS the mapping M is metrically regular in the vicinity of \bar{y} .

PROOF. The proof follows from Gfrerer and Klatte [7, Proposition 1] and the observation following Definition 4 therein. \Box

The following example demonstrates that metric regularity in the vicinity of \bar{y} holds for a broad class of inequality systems, even when MFCQ is not fulfilled.

EXAMPLE 1. Let $\Gamma \subset \mathbb{R}^2$ be given by

$$q(\mathbf{y}) = \begin{pmatrix} -\mathbf{y}_2 \\ \mathbf{y}_2 - \mathbf{y}_1^d \end{pmatrix}$$

for fixed exponent $d \in \mathbb{N}\setminus\{0\}$ and let $\bar{y} = 0$. Then it is easy to see that the corresponding mapping M is metrically regular near $(\bar{y}, 0)$, i.e., MFCQ holds at \bar{y} only in case when d = 1. On the other hand, SOSCMS holds when d = 2, because for every $0 \neq u \in T_{\Gamma}^{\text{lin}}(\bar{y}) = \mathbb{R} \times \{0\}$ and every $0 \neq \lambda \in \text{ker}(\nabla q(\bar{y})^T) \cap \hat{N}_{\mathbb{R}^l_-}(q(\bar{y})) = \{(\lambda_1, \lambda_2) \in \mathbb{R}^{2}_+ | \lambda_1 = \lambda_2\}$ we have $u^T \nabla^2 (\lambda^T q)(\bar{y})u = -2\lambda_2 u_1^2 < 0$ and thus SOSCMS follows. However, M is metrically regular in the vicinity of \bar{y} for every $d \in \mathbb{N} \setminus \{0\}$. This follows from the fact that at every point $y \in \Gamma \setminus \{\bar{y}\}$ at most one constraint is active and the gradient of this active constraint is bounded away from 0. Δ

3. Notation and auxiliary results. Given elements $y \in \Gamma$ and $y^* \in \hat{N}_{\Gamma}(y)$, we define by

$$\Lambda(y, y^*) := \{\lambda \in \hat{N}_{\mathbb{R}^l} (q(y)) \mid \nabla q(y)^T \lambda = y^*\},\$$

the set of Lagrange multipliers associated with (y, y^*) . Moreover

$$K(y, y^*) := T_{\Gamma}(y) \cap (y^*)^{\perp}$$

stands for the *critical cone* to Γ at y with respect to y^* .

For a given reference pair $(\bar{y}, \bar{y}^*), \bar{y} \in \Gamma, \bar{y}^* \in \hat{N}_{\Gamma}(\bar{y})$, fixed throughout this paper, we shortly set $\overline{\mathcal{F}} := \mathcal{F}(\bar{y})$, $\bar{\Lambda} := \Lambda(\bar{y}, \bar{y}^*)$ and $\bar{K} := K(\bar{y}, \bar{y}^*)$. Furthermore we employ the set

$$\overline{\mathcal{N}} := \{ v \in \mathbb{R}^m \mid \nabla q_i(\overline{y}) v = 0, \ i \in \overline{\mathcal{F}} \}$$

(nullspace of gradients of constraints active at \bar{y}). Given a multiplier $\lambda \in \hat{N}_{\mathbb{R}^{l}}(q(\bar{y}))$ we introduce the index sets

$$I^+(\lambda) := \{i \in \{1, \ldots, l\} \mid \lambda_i > 0\}, \qquad \overline{I}^0(\lambda) := \overline{\mathcal{F}} \setminus I^+(\lambda),$$

the sets of strongly and weakly active constraints. Apart from them, we will be working with

$$ar{I}^+ = igcup_{\lambda \in ar{\Lambda}} I^+(\lambda), \qquad ar{I}^0 := \overline{\mathscr{F}} ackslash ar{I}^+$$

With a direction $v \in T_{\Gamma}^{\text{lin}}(\bar{y})$ let us now associate the *directional multiplier set*

$$\bar{\Lambda}(v) := \underset{\lambda \in \bar{\Lambda}}{\arg\max} v^T \nabla^2 (\lambda^T q)(\bar{y}) v.$$

Directly from the definition of metric subregularity, one can infer that under metric subregularity of M at (y, 0) one has

$$T_{\Gamma}(y) = T_{\Gamma}^{\text{lin}}(y);$$

cf. also Henrion and Outrata [9, Proposition 1], and thus

$$K(y, y^*) = T_{\Gamma}^{\ln}(y) \cap \{y^*\}^{\perp} = \{ w \in \mathbb{R}^m \mid \nabla q_i(y)w \le 0, \ i \in \mathcal{I}(y), \ y^Tw = 0 \}.$$
(13)

Further, it follows that under this condition the regular normal cone to Γ at y amounts to

$$\hat{N}_{\Gamma}(y) = \nabla q(y)^T \hat{N}_{\mathbb{R}^l_{-}}(q(y))$$

and consequently $\Lambda(y, y^*) \neq \emptyset$. In the rest of this section, the metric subregularity of M at $(\bar{y}, 0)$ will be assumed.

LEMMA 1. Let $v \in \overline{K}$, $\lambda \in \overline{\Lambda}$ and assume that M is metrically subregular at $(\overline{y}, 0)$. Then

$$\hat{N}_{\bar{K}}(v) = \left\{ \nabla q(\bar{y})^T \mu \mid \mu^T \nabla q(\bar{y})v = 0, \, \mu \in T_{\hat{N}_{\mathbb{R}^l}(q(\bar{y}))}(\lambda) \right\}.$$

PROOF. Note that $\hat{N}_{\bar{K}}(v) = \bar{K}^{\circ} \cap \{v\}^{\perp}$ and, by virtue of the Farkas Lemma,

$$\begin{split} \bar{K}^{\circ} &= \left\{ w \in \mathbb{R}^{m} \mid \nabla q_{i}(\bar{y})w \leq 0, i \in \overline{\mathcal{F}}, \, \bar{y}^{*T}w = 0 \right\}^{\circ} = \left\{ \sum_{i \in \overline{\mathcal{F}}} \mu_{i} \nabla q_{i}(\bar{y}) + \alpha \bar{y}^{*} \mid \mu_{i} \geq 0, i \in \overline{\mathcal{F}}, \, \alpha \in \mathbb{R} \right\} \\ &= \nabla q(\bar{y})^{T} \hat{N}_{\mathbb{R}^{L}_{-}}(q(\bar{y})) + \mathbb{R} \bar{y}^{*}. \end{split}$$

Hence, for every $v^* \in \hat{N}_{\bar{K}}(v)$ there is some $\tilde{\mu} \in \hat{N}_{\mathbb{R}^l_-}(q(\bar{y}))$ and some $\alpha \in \mathbb{R}$ with $v^* = \nabla q(\bar{y})^T \tilde{\mu} + \alpha \bar{y}^* = \nabla q(\bar{y})^T (\tilde{\mu} + \alpha \lambda)$. Setting $\mu = \tilde{\mu} + \alpha \lambda$ we have $v^* = \nabla q(\bar{y})^T \mu$, $\mu^T \nabla q(\bar{y})v = v^{*T}v = 0$ and $\mu \in T_{\hat{N}_{\mathbb{R}^l_-}(q(\bar{y}))}(\lambda)$, where the last relation follows from the fact that for t > 0 sufficiently small we have $1 + \alpha t > 0$ and thus $\lambda + t\mu = (1 + \alpha t)\lambda + t\tilde{\mu} \in \hat{N}_{\mathbb{R}^l_-}(q(\bar{y}))$.

Conversely, let $\mu \in T_{\hat{N}_{\mathbb{R}^{l}_{-}}(q(\bar{y}))}(\lambda)$ with $\mu^{T} \nabla q(\bar{y})^{T} v = 0$ be arbitrarily fixed. Then there is some t > 0 such that $\lambda + t\mu \in \hat{N}_{\mathbb{R}^{l}_{-}}(q(\bar{y}))$ and therefore for all $w \in \bar{K} = T_{\Gamma}^{\mathrm{lin}}(\bar{y}) \cap \{\bar{y}^{*}\}^{\perp} \subset T_{\Gamma}^{\mathrm{lin}}(\bar{y})$ we have

$$0 \ge (\lambda + t\mu)^T \nabla q(\bar{y}) w = \bar{y}^{*T} w + t\mu^T \nabla q(\bar{y}) w = t (\nabla q(\bar{y})^T \mu)^T w$$

showing $\nabla q(\bar{y})^T \mu \in \bar{K}^\circ$. Together with $(\nabla q(\bar{y})^T \mu)^T v = 0$ we conclude $(\nabla q(\bar{y})^T \mu) \in \hat{N}_{\bar{K}}(v)$. \Box

LEMMA 2. Assume that M is metrically subregular at $(\bar{y}, 0)$. Then there is some $\tilde{\lambda} \in \bar{\Lambda}$ such that $I^+(\tilde{\lambda}) = \bar{I}^+$. Further we have

$$\bar{K} = \left\{ v \in \mathbb{R}^m \middle| \begin{array}{l} \nabla q_i(\bar{y})v = 0, \ i \in I^+ \\ \nabla q_i(\bar{y})v \le 0, \ i \in \bar{I}^0 \end{array} \right\}$$

and there is some $v \in \overline{K}$ satisfying

$$\nabla q_i(\bar{y})v = 0, \quad i \in \bar{I}^+, \qquad \nabla q_i(\bar{y})v < 0, \quad i \in \bar{I}^0.$$

$$\tag{14}$$

PROOF. Since \bar{I}^+ is a finite index set, there are $\lambda^i \in \bar{\Lambda}$, i = 1, ..., N, such that $\bar{I}^+ = \bigcup_{i=1}^N I^+(\lambda^i)$. Setting $\tilde{\lambda} := (1/N) \sum_{i=1}^N \lambda^i$ it easily follows that $\tilde{\lambda} \in \bar{\Lambda}$ and $I^+(\tilde{\lambda}) = \bar{I}^+$. The second assertion follows from the equivalences

$$\begin{split} v \in \bar{K} & \Leftrightarrow \quad \left(v \in T_{\Gamma}^{\mathrm{lin}}(\bar{y}) \wedge 0 = \bar{y}^{*^{T}} v = (\nabla q(\bar{y})^{T} \tilde{\lambda})^{T} v = \tilde{\lambda}^{T} \nabla q(\bar{y}) v = \sum_{i \in I^{+}(\tilde{\lambda})} \tilde{\lambda}_{i} \nabla q_{i}(\bar{y}) v \right) \\ & \Leftrightarrow \quad (v \in T_{\Gamma}^{\mathrm{lin}}(\bar{y}) \wedge \nabla q_{i}(\bar{y}) v = 0, i \in I^{+}(\tilde{\lambda}) = \bar{I}^{+}). \end{split}$$

We prove the last statement by contraposition. Assuming that the system

$$\nabla q_i(\bar{y})v = 0, \quad i \in \bar{I}^+, \qquad \nabla q_i(\bar{y})v \le -1, \quad i \in \bar{I}^0$$
(15)

does not have a solution, by the Farkas lemma there is some $\mu \in \mathbb{R}^{l}$ such that $\nabla q(\bar{y})^{T} \mu = 0$, $\mu_{i} = 0$, $i \notin \overline{\mathcal{F}}$, $\mu_{i} \geq 0$, $i \in \overline{I}^{0}$ and $\sum_{i \in \overline{I}^{0}} \mu_{i} > 0$. It follows that $\tilde{\lambda} + t\mu \in \overline{\Lambda}$ for some t > 0 and from $\sum_{i \in \overline{I}^{0}} \mu_{i} > 0$ we conclude that there must be some index $i \in \overline{I}^{0}$ with $\tilde{\lambda}_{i} + t\mu_{i} > 0$ implying $i \in \overline{I}^{+}$, a contradiction. Hence the system (15) has a solution, and this completes the proof. \Box

Consider for every $v \in \overline{K}$ the linear optimization problem

LP(v) min
$$-v^T \nabla^2 (\lambda^T q)(\bar{y}) v$$
 subject to $\lambda \in \Lambda$

together with its dual program

DP(v) max
$$\bar{y}^{*T}z$$
 subject to $\nabla q_i(\bar{y})z \leq -v^T \nabla^2 q_i(\bar{y})v, \quad i \in \overline{\mathcal{F}}.$

Then, by definition, $\overline{\Lambda}(v)$ is the solution set of LP(v) and, by duality theory of linear programming, $\overline{\Lambda}(v) \neq \emptyset$ if and only if DP(v) is solvable. Further, given $\lambda \in \overline{\Lambda}$ and z feasible for DP(v), we have $\lambda \in \overline{\Lambda}(v)$ and z solves DP(v) if and only if

$$\lambda_i (\nabla q_i(\bar{y})z + v^T \nabla^2 q_i(\bar{y})v) = 0, \quad i \in \overline{\mathcal{F}}.$$
(16)

LEMMA 3. For every $\overline{v} \in \overline{K}$, there is a neighborhood U of \overline{v} such that

$$\overline{\Lambda}(v) \subset \overline{\Lambda}(\overline{v}), \quad \forall v \in U \cap \overline{K}.$$

PROOF. If $\overline{\Lambda}(\overline{v}) = \emptyset$, we conclude from Bank et al. [1, Theorems 5.4.1, 5.4.2] that $\overline{\Lambda}(v) = \emptyset$ for all v belonging to some neighborhood U of \overline{v} . Now assume $\overline{\Lambda}(\overline{v}) \neq \emptyset$. Again by Bank et al. [1, Theorems 5.4.1, 5.4.2] for every $\epsilon > 0$ there is some neighborhood U_{ϵ} such that $d(\lambda, \overline{\Lambda}(\overline{v})) < \epsilon$ for every $v \in U_{\epsilon}$ and every $\lambda \in \overline{\Lambda}(v)$. Further, we know that the solution set of a linear optimization problem is a face of the feasible set. Combining both properties we see that for all v near \overline{v} the solution set $\overline{\Lambda}(v)$ is a face of $\overline{\Lambda}(\overline{v})$, provided it is not empty. \Box

In what follows, we denote by \mathscr{C} the set of extreme points of the polyhedron $\overline{\Lambda}$. The polyhedron $\overline{\Lambda}$ can be represented as the sum of the convex hull of its extreme points and its recession cone $\mathscr{R} := \{\lambda \in \hat{N}_{\mathbb{R}^{l}}(q(\overline{y})) \mid \nabla q(\overline{y})^{T}\lambda = 0\}$, i.e., $\overline{\Lambda} = \operatorname{conv} \mathscr{C} + \mathscr{R}$. From the theory of linear programming it is well known that $\overline{\Lambda}(v) \neq \emptyset$ if and only if

$$v^T \nabla^2 (\lambda^T q)(\bar{y}) v \leq 0, \quad \forall \lambda \in \mathcal{R}$$

In this case, the set $\bar{\Lambda}(v) \cap \mathscr{C}$ is not empty and contains exactly the extreme points of $\bar{\Lambda}(v)$. In what follows, we denote by $\bar{\Lambda}^{\mathscr{C}}(v)$ the compact convex polyhedron $\bar{\Lambda}^{\mathscr{C}}(v) := \bar{\Lambda}(v) \cap \operatorname{conv} \mathscr{C}$.

4. Graphical derivative and regular coderivative of \hat{N}_{Γ} . We denote by $\mathcal{T}(\bar{y}, \bar{y}^*)$ the set

$$\mathcal{T}(\bar{y}, \bar{y}^*) := \{(v, v^*) \mid \exists \lambda \in \bar{\Lambda}(v) \colon v^* \in \nabla^2(\lambda^T q)(\bar{y})v + \hat{N}_{\bar{K}}(v)\}.$$

THEOREM 1. Assume that M is metrically subregular at $(\bar{y}, 0)$. Then

$$\mathcal{T}(\bar{y}, \bar{y}^*) \subset T_{\text{sph}\,\hat{N}_{\text{r}}}(\bar{y}, \bar{y}^*) \tag{17}$$

and equality holds if in addition M is metrically regular in the vicinity of \bar{y} .

PROOF. To show (17) let $(v, v^*) \in \mathcal{T}(\bar{y}, \bar{y}^*)$ be arbitrarily fixed. To show $(v, v^*) \in T_{gph\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$ we must prove the existence of sequences $(t_k) \downarrow 0$ and $(y_k) \rightarrow^{\Gamma} \bar{y}$ such that

$$\lim_{k \to \infty} \frac{\bar{y} + t_k v - y_k}{t_k} = 0, \qquad \lim_{k \to \infty} \frac{\mathrm{d}(\bar{y}^* + t_k v^*, \hat{N}_{\Gamma}(y_k))}{t_k} = 0$$

Let $\lambda \in \overline{\Lambda}(v)$ such that $v^* \in \nabla^2(\lambda^T q)(\overline{y})v + \widehat{N}_{\overline{K}}(v)$ and choose $\alpha > 0$ so small that $\alpha \|\nabla^2(\lambda^T q)(\overline{y})\| < \frac{1}{2}$. It follows that $2I + \nabla^2((\alpha\lambda)^T q)(\overline{y})$ is positive definite and hence, by applying the standard second-order sufficient conditions of nonlinear programming (see, e.g., Bonnans and Shapiro [2, Proposition 5.48]), we can conclude that there is some positive radius $\rho > 0$ such that \overline{y} is the unique global solution of the problem

$$\min_{y} \|\bar{y} + \alpha \bar{y}^* - y\|^2 \quad \text{subject to } q(y) \le 0, \ \|y - \bar{y}\| \le \rho.$$

Since λ solves LP(v), by duality theory of linear programming as discussed in the previous section, there is some vector z solving DP(v) with

$$\nabla q_i(\bar{y})z + v^T \nabla^2 q_i(\bar{y})v \le 0, \quad \lambda_i(\nabla q_i(\bar{y})z + v^T \nabla^2 q_i(\bar{y})v) = 0, \qquad i \in \overline{\mathcal{F}}.$$
(18)

Since $\lambda_i = 0$, $i \notin \overline{\mathcal{F}}$, we obtain

$$\lambda^T \nabla q(\bar{y}) z + v^T \nabla^2 (\lambda^T q)(\bar{y}) v = 0.$$
⁽¹⁹⁾

By Lemma 1 there is some $\mu \in T_{\hat{N}_{\mathbb{R}^{L}}(q(\bar{y}))}(\lambda) \cap (\nabla q(\bar{y})v)^{\perp}$ with $v^{*} = \nabla^{2}(\lambda^{T}q)(\bar{y})v + \nabla q(\bar{y})^{T}\mu$ and thus

$$v^{*^T}v = v^T \nabla^2 (\lambda^T q)(\bar{y})v + \mu^T \nabla q(\bar{y})v = v^T \nabla^2 (\lambda^T q)(\bar{y})v.$$
⁽²⁰⁾

Since $\hat{N}_{\mathbb{R}^{l}_{-}}(q(\bar{y}))$ is a convex polyhedron and therefore $T_{\hat{N}_{\mathbb{R}^{l}_{-}}(q(\bar{y}))}(\lambda) = \mathbb{R}_{+}(\hat{N}_{\mathbb{R}^{l}_{-}}(q(\bar{y})) - \lambda)$, the condition $\mu \in T_{\hat{N}_{\mathbb{R}^{l}_{-}}(q(\bar{y}))}(\lambda)$ ensures the existence of some $\bar{t} > 0$ such that $\lambda + t\mu \in \hat{N}_{\mathbb{R}^{l}_{-}}(q(\bar{y}))$ for all $t \in [0, \bar{t}]$ and since $q_i(\bar{y}) < 0$, $i \notin \overline{\mathcal{F}}$, we can also assume that for every $t \in [0, \bar{t}]$ we have $q_i(\bar{y} + tv + \frac{1}{2}t^2z) < 0$, $i \notin \overline{\mathcal{F}}$. We now consider for each $t \in [0, \bar{t}]$ a global solution y_t of the optimization problem

$$\min \|\bar{y} + tv + \frac{1}{2}t^2z + \alpha(\bar{y}^* + tv^*) - y\|^2 \quad \text{subject to } y \in \Gamma, \ \|y - \bar{y}\| \le \rho.$$

To show the inclusion $(v, v^*) \in T_{\text{gph}\,\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$ it suffices to show

$$\lim_{t \downarrow 0} \frac{\bar{y} + tv - y_t}{t} = 0$$
(21)

because then for all t > 0 sufficiently small we have $||y_t - \bar{y}|| < \rho$ and therefore the standard optimality condition at y_t reads as

$$\alpha(\bar{y}^* + tv^*) + t\left(\frac{\bar{y} + tv - y_t}{t} + \frac{1}{2}tz\right) \in \hat{N}_{\Gamma}(y_t).$$

This, because $\hat{N}_{\Gamma}(y_t)$ is a cone, implies that

$$\lim_{t\downarrow 0} \frac{\mathrm{d}(\bar{y}^* + tv^*, \hat{N}_{\Gamma}(y_t))}{t} = 0.$$

Our choice of α and ρ guarantees that $y_0 = \bar{y}$ and, by using Bonnans and Shapiro [2, Proposition 4.4], we conclude $\lim_{t \downarrow 0} y_t = \bar{y}$. Taking into account (18) and $\nabla q_i(\bar{y})v \le 0$, $i \in \overline{\mathcal{F}}$, because of $v \in \bar{K}$ and (13), we obtain

$$q_i\left(\bar{y}+tv+\frac{1}{2}t^2z\right) = q_i(\bar{y})+t\nabla q_i(\bar{y})v+\frac{1}{2}t^2(\nabla q_i(\bar{y})z+v^T\nabla^2 q_i(\bar{y})v)+o(t^2) \le o(t^2), \quad i\in\overline{\mathcal{F}},$$

and since $q_i(\bar{y} + tv + \frac{1}{2}t^2z) < 0$, $i \notin \overline{\mathcal{F}}$, and M is assumed to be metrically subregular at $(\bar{y}, 0)$, we can find for every $t \in [0, \bar{t}]$ some point $\tilde{y}_t \in \Gamma$ with $\|\bar{y} + tv + \frac{1}{2}t^2z - \tilde{y}_t\| = o(t^2)$. Hence

$$\left\|\bar{y} + tv + \frac{1}{2}t^{2}z + \alpha(\bar{y}^{*} + tv^{*}) - y_{t}\right\|^{2} \le \left\|\bar{y} + tv + \frac{1}{2}t^{2}z + \alpha(\bar{y}^{*} + tv^{*}) - \tilde{y}_{t}\right\|^{2}$$

for all $t \ge 0$ sufficiently small, implying

$$\left\|\bar{y} + tv + \frac{1}{2}t^{2}z - y_{t}\right\|^{2} + 2\alpha(\bar{y}^{*} + tv^{*})^{T}(\bar{y} + tv + \frac{1}{2}t^{2}z - y_{t}) \le o(t^{2}).$$
(22)

From $\lambda + t\mu \in \hat{N}_{\mathbb{R}^{l}_{-}}(q(\bar{y})), q(y_{t}) - q(\bar{y}) \in T_{\mathbb{R}^{l}_{-}}(q(\bar{y}))$ and $v^{*} = \nabla^{2}(\lambda^{T}q)(\bar{y})v + \nabla q(\bar{y})^{T}\mu$ we obtain $0 \ge (\lambda + t\mu)^{T}(q(y_{t}) - q(\bar{y}))$ $= (\lambda + t\mu)^{T}\nabla q(\bar{y})(y_{t} - \bar{y}) + \frac{1}{2}(y_{t} - \bar{y})^{T}\nabla^{2}(\lambda^{T}q)(\bar{y})(y_{t} - \bar{y}) + \frac{t}{2}(y_{t} - \bar{y})^{T}\nabla^{2}(\mu^{T}q)(\bar{y})(y_{t} - \bar{y}) + o(||y_{t} - \bar{y}||^{2})$ $= (\lambda + t\mu)^{T}\nabla q(\bar{y})(y_{t} - \bar{y}) + \frac{1}{2}(y_{t} - \bar{y})^{T}\nabla^{2}(\lambda^{T}q)(\bar{y})(y_{t} - \bar{y}) + o(||y_{t} - \bar{y}||^{2})$ $= (\bar{y}^{*} + tv^{*})^{T}(y_{t} - \bar{y}) - tv^{T}\nabla^{2}(\lambda^{T}q)(\bar{y})(y_{t} - \bar{y}) + \frac{1}{2}(y_{t} - \bar{y})^{T}\nabla^{2}(\lambda^{T}q)(\bar{y})(y_{t} - \bar{y}) + o(||y_{t} - \bar{y}||^{2})$

and, consequently, by taking into account $\bar{y}^{*T}v = 0$ and relations (19), (20),

$$\begin{split} &(\bar{y}^{*} + tv^{*})^{T} \left(\bar{y} + tv + \frac{1}{2} t^{2} z - y_{t} \right) \\ &= (\bar{y}^{*} + tv^{*})^{T} (\bar{y} - y_{t}) + t \bar{y}^{*T} v + \frac{1}{2} t^{2} \bar{y}^{*T} z + t^{2} v^{*T} v + o(t^{2}) \\ &\geq tv^{T} \nabla^{2} (\lambda^{T} q) (\bar{y}) (\bar{y} - y_{t}) + \frac{1}{2} (y_{t} - \bar{y})^{T} \nabla^{2} (\lambda^{T} q) (\bar{y}) (y_{t} - \bar{y}) + t \bar{y}^{*T} v + \frac{1}{2} t^{2} \lambda^{T} \nabla q(\bar{y}) z + t^{2} v^{T} \nabla^{2} (\lambda^{T} q) (\bar{y}) v \\ &+ o(t^{2}) + o(||y_{t} - \bar{y}||^{2}) \\ &= tv^{T} \nabla^{2} (\lambda^{T} q) (\bar{y}) (\bar{y} - y_{t}) + \frac{1}{2} (y_{t} - \bar{y})^{T} \nabla^{2} (\lambda^{T} q) (\bar{y}) (y_{t} - \bar{y}) + \frac{1}{2} t^{2} v^{T} \nabla^{2} (\lambda^{T} q) (\bar{y}) v + o(t^{2}) + o(||y_{t} - \bar{y}||^{2}) \\ &= \frac{1}{2} (\bar{y} + tv - y_{t})^{T} \nabla^{2} (\lambda^{T} q) (\bar{y}) (\bar{y} + tv - y_{t}) + o(t^{2}) + o(||y_{t} - \bar{y}||^{2}) \\ &\geq -\frac{1}{2} ||\nabla^{2} (\lambda^{T} q) (\bar{y})|||\bar{y} + tv - y_{t}||^{2} + o(t^{2}) + o(||y_{t} - \bar{y}||^{2}). \end{split}$$

Since $\alpha \|\nabla^2 (\lambda^T q)(\bar{y})\| < \frac{1}{2}$, it follows that

$$\begin{split} \|\bar{y} + tv + \frac{1}{2}t^{2}z - y_{t}\|^{2} &- \frac{1}{2}\|\bar{y} + tv - y_{t}\|^{2} \\ &\leq \|\bar{y} + tv + \frac{1}{2}t^{2}z - y_{t}\|^{2} + 2\alpha(\bar{y}^{*} + tv^{*})^{T}(\bar{y} + tv + \frac{1}{2}t^{2}z - y_{t}) + o(t^{2}) + o(\|y_{t} - \bar{y}\|^{2}) \\ &\leq o(t^{2}) + o(\|y_{t} - \bar{y}\|^{2}), \end{split}$$

where the last inequality follows from (22), and

$$\frac{1}{2} \|\bar{y} + tv - y_t\|^2 \le o(t^2) + o(\|y_t - \bar{y}\|^2).$$
(23)

Hence there is some $\tilde{t} > 0$ such that $\frac{1}{2} \| \bar{y} + tv - y_t \|^2 \le \frac{1}{4} (t^2 + \| y_t - \bar{y} \|^2)$, $\forall t \in [0, \tilde{t}]$. After rearranging we obtain $\frac{1}{4} \| \bar{y} - y_t \|^2 + tv^T (\bar{y} - y_t) + \frac{1}{2} t^2 \| v \|^2 \le \frac{1}{4} t^2$ showing

$$\frac{1}{4} \|\bar{y} + 2tv - y_t\|^2 = \frac{1}{4} \|\bar{y} - y_t\|^2 + tv^T (\bar{y} - y_t) + t^2 \|v\|^2 \le \frac{1}{4} t^2 (1 + 2\|v\|^2)$$

and $\|\bar{y} - y_t\| \le t(2\|v\| + \sqrt{1 + 2\|v\|^2})$. From (23) we conclude that (21) holds and therefore $(v, v^*) \in T_{\text{gph}\,\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$ follows.

Next we show that the reverse inclusion $\mathcal{T}(\bar{y}, \bar{y}^*) \supset T_{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$ is valid under the additional assumption that M is metrically regular in the vicinity of \bar{y} . Let $\kappa > 0$ denote the modulus of metric regularity according to Definition 2, let $(v, v^*) \in T_{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$ and consider sequences $(t_k) \downarrow 0$, $(v_k) \rightarrow v$ and $(v_k^*) \rightarrow v^*$ such that $y_k^* := \bar{y}^* + t_k v_k^* \in \hat{N}_{\Gamma}(y_k)$, where $y_k := \bar{y} + t_k v_k$. By passing to a subsequence if necessary we can assume that there is some index set $\tilde{\mathcal{F}} \subset \bar{\mathcal{F}}$ such that $\mathcal{F}(y_k) = \tilde{\mathcal{F}}$ holds for all k and that for every k with $y_k \neq \bar{y}$ the multifunction M is metrically regular with modulus κ near $(y_k, 0)$. For every $i \in \bar{\mathcal{F}}$ we have

$$q_i(y_k) = q_i(\bar{y}) + t_k \nabla q_i(\bar{y})v_k + o(t_k) = t_k \nabla q_i(\bar{y})v_k + o(t_k) \begin{cases} = 0 & \text{if } i \in \tilde{\mathcal{F}}, \\ \le 0 & \text{if } i \in \overline{\mathcal{F}} \setminus \tilde{\mathcal{F}} \end{cases}$$

Dividing by t_k and passing to the limit we obtain

$$\nabla q_i(\bar{y})v \begin{cases} = 0 & \text{if } i \in \tilde{\mathcal{F}}, \\ \leq 0 & \text{if } i \in \overline{\mathcal{F}} \backslash \tilde{\mathcal{F}}. \end{cases}$$
(24)

Next, consider for each $y^* \in \mathbb{R}^m$ the set

$$\Psi_{\tilde{\mathcal{J}}}(y^*) := \left\{ \lambda \in \mathbb{R}^l \mid \nabla q(\bar{y})^T \lambda = y^*, \ \lambda_i \ge 0, \ i \in \tilde{\mathcal{J}}, \ \lambda_i = 0, \ i \notin \tilde{\mathcal{J}} \right\}.$$
(25)

By Hoffman's Lemma there is some constant β such that for every $\lambda \in \mathbb{R}^l$ and every $y^* \in \mathbb{R}^m$ with $\Psi_{\tilde{\mathcal{F}}}(y^*) \neq \emptyset$ one has

$$d(\lambda, \Psi_{\tilde{\mathcal{F}}}(y^*)) \le \beta \bigg(\|\nabla q(\bar{y})^T \lambda - y^*\| - \sum_{i \in \tilde{\mathcal{F}}} \min\{\lambda_i, 0\} + \sum_{i \notin \tilde{\mathcal{F}}} |\lambda_i| \bigg).$$
(26)

If $y_k \neq \bar{y}$ then, as a consequence of the assumption that M is metrically regular in the vicinity of \bar{y} , there is some multiplier $\lambda^k \in \hat{N}_{\mathbb{R}^L}(q(y_k))$ with $y_k^* = \nabla q(y_k)^T \lambda^k$ and using Proposition 1, we have $\lambda^k = 0$ when $y_k^* = 0$ and

$$\frac{\|\lambda^k\|}{\|y_k^*\|} = \frac{1}{\|\nabla q(y_k)^T (\lambda^k / \|\lambda^k\|)\|} \le \kappa, \quad \text{whenever } y_k^* \neq 0,$$

showing $\|\lambda^k\| \leq \kappa \|y_k^*\|$. On the other hand, if $y_k = \bar{y}$, since M is assumed to be metrically subregular at $(\bar{y}, 0)$, there is also some multiplier $\lambda^k \in \hat{N}_{\mathbb{R}^l_-}(q(y_k))$ with $y_k^* = \nabla q(y_k)^T \lambda^k$ and by using (26), we can choose λ^k such that $\|\lambda^k\| = d(0, \Psi_{\tilde{\mathcal{F}}}(y_k^*)) \leq \beta \|y_k^*\|$. Hence we can assume that the sequence (λ^k) is uniformly bounded by some constant c_1 and, by passing to a subsequence if necessary, we can assume that (λ^k) converges to $\bar{\lambda}$. Because of the definition of λ^k we have $\nabla q(\bar{y})^T \bar{\lambda} = 0$, $\bar{\lambda}_i \geq 0$ with $i \notin \tilde{\mathcal{F}}$, and $\bar{\lambda}_i = 0$ with $i \notin \tilde{\mathcal{F}}$, which ensures $\bar{\lambda} \in \Psi_{\tilde{\mathcal{F}}}(\bar{y}^*)$. Since

$$\nabla q(\bar{y})^T \lambda^k - \bar{y}^* = t_k v_k^* + (\nabla q(\bar{y}) - \nabla q(y_k))^T \lambda^k$$

and $\|\nabla q(\bar{y}) - \nabla q(y_k)\| \leq c_2 \|y_k - \bar{y}\| = c_2 t_k \|v_k\|$ for some constant $c_2 \geq 0$, by using (26) once more we can find for each k some $\tilde{\lambda}^k \in \Psi_{\tilde{\mathcal{F}}}(\bar{y}^*) \subset \bar{\Lambda}$ with $\|\tilde{\lambda}^k - \lambda^k\| \leq \beta t_k (\|v_k^*\| + c_1 c_2 \|v_k\|)$. Taking $\mu^k := (\lambda_k - \tilde{\lambda}_k)/t_k$, we have that (μ^k) is uniformly bounded. By passing to subsequences if necessary we can assume that both sequences $(\tilde{\lambda}^k)$ and (μ^k) are convergent to some $\tilde{\lambda} \in \Psi_{\tilde{\mathcal{F}}}(\bar{y}^*) \subset \bar{\Lambda}$ and some μ . Since $\lambda_i^k = \tilde{\lambda}_i^k = 0$, $i \notin \tilde{\mathcal{F}}$, we have $(\mu^k)^T \nabla q(\bar{y})v = 0$, $\forall k$ implying $\mu \in (\nabla q(\bar{y})v)^{\perp}$.

Taking into account $(\hat{\lambda}^k)^T q(y_k) = 0, \forall k$, we obtain

$$0 = \lim_{k \to \infty} \frac{(\lambda^k)^T q(y_k)}{t_k} = \lim_{k \to \infty} (\tilde{\lambda}^k)^T \nabla q(\bar{y}) v_k = \bar{y}^{*T} v,$$

which, together with (24), shows $v \in \overline{K}$.

Further, we have for all $\lambda \in \Lambda$

$$0 \leq (\tilde{\lambda}^{k} - \lambda)^{T} q(y_{k}) = (\tilde{\lambda}^{k} - \lambda)^{T} (q(\bar{y}) + t_{k} \nabla q(\bar{y}) v_{k} + \frac{1}{2} t_{k}^{2} v_{k}^{T} \nabla^{2} q(\bar{y}) v^{k} + o(t_{k}^{2}))$$

= $(\tilde{\lambda}^{k} - \lambda)^{T} (\frac{1}{2} t_{k}^{2} v_{k}^{T} \nabla^{2} q(\bar{y}) v^{k} + o(t_{k}^{2})).$

Dividing by t_k^2 and passing to the limit, we obtain $(\tilde{\lambda} - \lambda)^T v^T \nabla^2 q(\bar{y}) v \ge 0$, $\forall \lambda \in \bar{\Lambda}$ and hence $\tilde{\lambda} \in \bar{\Lambda}(v)$ follows. Since

$$y_k^* = \nabla q(\bar{y})^T \tilde{\lambda}^k + t_k v_k^* = \nabla q(y_k)^T \lambda^k$$

we obtain

$$v^* = \lim_{k \to \infty} v_k^* = \lim_{k \to \infty} \frac{\nabla q(y_k)^T \lambda^k - \nabla q(\bar{y})^T \tilde{\lambda}^k}{t_k}$$
$$= \lim_{k \to \infty} \frac{(\nabla q(y_k) - \nabla q(\bar{y}))^T \tilde{\lambda}^k + \nabla q(y_k)^T (\lambda^k - \tilde{\lambda}^k)}{t_k}$$
$$= \nabla^2 (\tilde{\lambda}^T q) (\bar{y}) v + \nabla q(\bar{y})^T \mu.$$

If

$$\mu \in T_{\hat{N}_{\mathbb{R}^{l}_{-}}(q(\bar{y}))}(\tilde{\lambda}) = \left\{ \eta \in \mathbb{R}^{l} \middle| \eta_{i} \begin{cases} \in \mathbb{R} & \text{if } i \in \overline{\mathcal{F}}, \ \tilde{\lambda}_{i} > 0 \\ \geq 0 & \text{if } i \in \overline{\mathcal{F}}, \ \tilde{\lambda}_{i} = 0 \\ = 0 & \text{if } i \notin \overline{\mathcal{F}} \end{cases} \right\},$$

the assertion is proved by virtue of Lemma 1. Otherwise the set $J := \{i \in \tilde{\mathcal{F}} \mid \tilde{\lambda}_i = 0, \mu_i < 0\}$ is not empty, where we have taken into account that $\tilde{\mathcal{F}} \subset \overline{\mathcal{F}}$ and for all $i \notin \tilde{\mathcal{F}}$ we have $\tilde{\lambda}_i^k = 0, \forall k, \tilde{\lambda}_i = 0$ and $\mu_i = 0$. Let us choose some index \bar{k} such that $(\lambda_i^{\bar{k}} - \tilde{\lambda}_i^{\bar{k}})/t_{\bar{k}} \le \mu_i/2, \forall i \in J$ and set $\tilde{\mu} := \mu + 2(\tilde{\lambda}^{\bar{k}} - \tilde{\lambda})/t_{\bar{k}}$. Then for all $i \notin \tilde{\mathcal{F}}$ we have $\tilde{\mu}_i = 0$, for all $i \notin \tilde{\mathcal{F}}$ with $\lambda_i = 0$ we have $\tilde{\mu}_i \ge \mu_i$ and for all $i \in J$ we have

$$\tilde{\mu}_i = \mu_i + 2(\tilde{\lambda}_i^{\bar{k}} - \tilde{\lambda}_i)/t_{\bar{k}} \ge \mu_i + 2(\tilde{\lambda}_i^{\bar{k}} - \lambda_i^{\bar{k}})/t_{\bar{k}} \ge 0$$

and therefore $\tilde{\mu} \in T_{\hat{N}_{\mathbb{R}^{l}_{-}}(q(\tilde{y}))}(\tilde{\lambda})$. Observing that $\nabla q(\tilde{y})^{T}\tilde{\mu} = \nabla q(\tilde{y})^{T}\mu$ because of $\tilde{\lambda}, \tilde{\lambda}^{\tilde{k}} \in \bar{\Lambda}$ and taking into account Lemma 1 completes the proof. \Box

Under the assumptions ensuring equality in (17) one has thus the formula

$$D\hat{N}_{\Gamma}(\bar{y}, \bar{y}^*)(v) = \{\nabla^2(\lambda^T q)(\bar{y})v \mid \lambda \in \bar{\Lambda}(v)\} + \hat{N}_{\bar{K}}(v), \quad v \in \mathbb{R}^m.$$

In this way we have recovered formula (3) under substantially weaker assumptions.

Let us turn our attention to the regular coderivative of \hat{N}_{Γ} .

PROPOSITION 4. Assume that $\overline{\Lambda} \neq \emptyset$. Then

$$\mathcal{T}(\bar{y}, \bar{y}^*)^\circ = \left\{ (w^*, w) \mid w \in \bar{K}, \, w^{*^T}v + w^T \nabla^2 (\lambda^T q)(\bar{y})v \le 0, \, v \in \bar{K}, \, \lambda \in \bar{\Lambda}(v) \right\}.$$

PROOF. By definition of the polar cone, we have $(w^*, w) \in \mathcal{T}(\bar{y}, \bar{y}^*)^\circ$ if and only if $w^{*T}v + w^Tv^* \leq 0$, $\forall (v, v^*) \in \mathcal{T}(\bar{y}, \bar{y}^*)$, i.e.,

$$w^{*^T}v + w^T(\nabla^2(\lambda^T q)(\bar{y})v + \xi^*) \le 0, \quad v \in \bar{K}, \ \lambda \in \bar{\Lambda}(v), \ \xi^* \in \hat{N}_{\bar{K}}(v).$$

Taking v = 0, $\lambda \in \overline{\Lambda}(0) = \overline{\Lambda} \neq \emptyset$, we obtain $w^T v^* \leq 0$, $\forall v^* \in \widehat{N}_{\overline{K}}(0) = \overline{K}^\circ$ showing $w \in \overline{K}$. Since $\widehat{N}_{\overline{K}}(v) = \{\xi^* \in \overline{K}^\circ \mid \xi^{*T}v = 0\} \subset \overline{K}^\circ$ we have $w^T \xi^* \leq 0$, $\forall \xi^* \in \widehat{N}_{\overline{K}}(v)$ and, because of $0 \in \widehat{N}_{\overline{K}}(v)$, we see that $(w^*, w) \in \mathcal{T}(\overline{y}, \overline{y}^*)^\circ$ if and only if $w \in \overline{K}$ and

$$w^{*^T}v + w^T \nabla^2 (\lambda^T q)(\bar{y})v \le 0, \quad v \in \bar{K}, \ \lambda \in \bar{\Lambda}(v).$$

By using Theorem 1 we obtain that $\hat{N}_{gph\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*) \subset \mathcal{T}(\bar{y}, \bar{y}^*)^{\circ}$ if M is metrically subregular at $(\bar{y}, 0)$ and this inclusion holds with equality if in addition M is metrically regular in the vicinity of \bar{y} . However, the representation of $\mathcal{T}(\bar{y}, \bar{y}^*)^{\circ}$ by Proposition 4 is not very useful in practice because of the simultaneous appearance of v and $\lambda \in \bar{\Lambda}(v)$.

We now define for each $v \in \overline{\mathcal{N}}$ the sets

$$\begin{split} \bar{\mathcal{W}}(v) &:= \left\{ w \in \bar{K} \mid w^T \nabla^2 ((\lambda^1 - \lambda^2)^T q)(\bar{y})v = 0, \, \forall \, \lambda^1, \, \lambda^2 \in \bar{\Lambda}(v) \right\}, \\ \tilde{\Lambda}^{\mathcal{E}}(v) &:= \begin{cases} \bar{\Lambda}^{\mathcal{E}}(v) & \text{if } v \neq 0, \\ \operatorname{conv} \left(\bigcup_{0 \neq u \in \bar{K}} \bar{\Lambda}^{\mathcal{E}}(u) \right) & \text{if } v = 0, \quad \bar{K} \neq \{0\} \end{cases} \end{split}$$

and for each $w \in \overline{K}$

$$\bar{L}(v;w) := \begin{cases} \{-\nabla^2(\lambda^T q)(\bar{y})w \mid \lambda \in \tilde{\Lambda}^{\mathcal{E}}(v)\} + \bar{K}^\circ & \text{if } \bar{K} \neq \{0\}, \\ \mathbb{R}^m & \text{if } \bar{K} = \{0\}. \end{cases}$$

Note that $\tilde{\Lambda}^{\mathscr{C}}(0)$ is a convex compact polyhedron, since there are only finitely many subsets of the finite set \mathscr{C} .

PROPOSITION 5. Assume that $\overline{\Lambda}(v) \neq \emptyset$, $\forall v \in \overline{K}$. Then

$$\mathcal{T}(\bar{y}, \bar{y}^*)^{\circ} \subset \left\{ (w^*, w) \middle| w \in \bigcap_{v \in \bar{\mathcal{N}}} {}^{\circ} \bar{\mathcal{W}}(v), w^* \in \bigcap_{v \in \bar{\mathcal{N}}} \bar{L}(v; w) \right\}$$
(27)

and equality holds, if either for any $0 \neq v_1, v_2 \in \overline{K}$ it holds $\overline{\Lambda}^{\mathscr{C}}(v_1) = \overline{\Lambda}^{\mathscr{C}}(v_2)$ or if $\overline{I}^+ = \overline{\mathcal{F}}$.

PROOF. If $\bar{K} = \{0\}$, by Proposition 4 we have $\mathcal{T}(\bar{y}, \bar{y}^*)^\circ = \mathbb{R}^m \times \{0\}$ and (27) holds with equality. Now assume that $\bar{K} \neq 0$, consider $(w^*, w) \in \mathcal{T}(\bar{y}, \bar{y}^*)^\circ$ and fix $v \in \bar{\mathcal{N}} \subset \bar{K}$. Then also $-v \in \bar{\mathcal{N}}, \bar{\Lambda}(v) = \bar{\Lambda}(-v)$ and by Proposition 4 we obtain $w^{*T}(\pm v) + w^T \nabla^2 (\lambda^T q)(\bar{y})(\pm v) \leq 0$, $\lambda \in \bar{\Lambda}(v)$ and therefore $w^{*T}v + w^T \nabla^2 (\lambda^T q)(\bar{y})v = 0$, $\lambda \in \bar{\Lambda}(v)$, implying $w \in \bar{\mathcal{W}}(v)$. By Lemma 3 together with the assumption of the proposition there is some compact convex neighborhood U of v such that $\emptyset \neq \bar{\Lambda}(u) \subset \bar{\Lambda}(v)$, $\forall u \in U \cap \bar{K}$ and therefore also $\emptyset \neq \bar{\Lambda}^{\mathcal{E}}(u) \subset \bar{\Lambda}^{\mathcal{E}}(v)$. We now claim that for every $u \in U \cap \bar{K}$ there is some $\lambda \in \tilde{\Lambda}^{\mathcal{E}}(v)$ such that

$$w^{*^T}u + w^T \nabla^2(\lambda^T q)(\bar{y})u \le 0.$$
(28)

Indeed, consider any $u \in U \cap \overline{K}$. If $v \neq 0$, then (28) holds for every $\lambda \in \overline{\Lambda}^{\mathfrak{E}}(u) \subset \overline{\Lambda}^{\mathfrak{E}}(v) = \widetilde{\Lambda}^{\mathfrak{E}}(v)$ by Proposition 4. If v = u = 0, then (28) is trivially fulfilled for arbitrary $\lambda \in \widetilde{\Lambda}^{\mathfrak{E}}(v) \neq \emptyset$. Finally, if v = 0 and $u \neq 0$, then again by Proposition 4, for every $\lambda \in \overline{\Lambda}^{\mathfrak{E}}(u) \subset \widetilde{\Lambda}^{\mathfrak{E}}(v)$ the inequality (28) holds. Hence our claim is proved and since both $U \cap \overline{K}$ and $\widetilde{\Lambda}^{\mathfrak{E}}(v)$ are nonempty compact convex sets, we obtain

$$0 \ge \max_{u \in U \cap \bar{K}} \min_{\lambda \in \tilde{\Lambda}^{\mathcal{E}}(v)} \left\{ w^{*^{T}} u + w^{T} \nabla^{2} (\lambda^{T} q)(\bar{y}) u \right\} = \min_{\lambda \in \tilde{\Lambda}^{\mathcal{E}}(v)} \max_{u \in U \cap \bar{K}} \left\{ w^{*^{T}} u + w^{T} \nabla^{2} (\lambda^{T} q)(\bar{y}) u \right\}.$$

We infer that there is some $\bar{\lambda} \in \tilde{\Lambda}^{\otimes}(v)$ such that $\max_{u \in U \cap \bar{K}} w^{*T} u + w^T \nabla^2 (\bar{\lambda}^T q)(\bar{y}) u \leq 0$. Together with $w^{*T}v + w^T \nabla^2 (\bar{\lambda}^T q)(\bar{y}) v = 0$ we conclude $(w^* + \nabla^2 (\bar{\lambda}^T q)(\bar{y}) w)^T (u - v) \leq 0$, $\forall u \in U \cap \bar{K}$ and thus $w^* + \nabla^2 (\bar{\lambda}^T q)(\bar{y}) w \in \hat{N}_{\bar{K}}(v)$. Taking into account that for $v \in \bar{N}$ we have $\hat{N}_{\bar{K}}(v) = \bar{K}^\circ$, we obtain $w^* \in \bar{L}(v; w)$. Since $v \in \bar{N}$ was arbitrarily fixed, inclusion (27) follows.

To prove equality, we may also assume that $\bar{K} \neq \{0\}$ and consider first the case when $\hat{\Lambda} := \bar{\Lambda}^{\mathscr{C}}(v_1) = \bar{\Lambda}^{\mathscr{C}}(v_2)$ for all $0 \neq v_1, v_2 \in \bar{K}$. Then we have $\tilde{\Lambda}^{\mathscr{C}}(v) = \hat{\Lambda}, \forall v \in \bar{\mathcal{N}}$ and the set on the right-hand side of the inclusion (27) amounts to

$$\Xi := \bigcup_{\lambda \in \hat{\Lambda}} \left\{ (w^*, w) \; \middle| \; w \in \bigcap_{v \in \bar{\lambda}} \bar{\mathscr{W}}(v), \; w^* \in -\nabla^2(\lambda^T q)(\bar{y})w + \bar{K}^\circ \right\}$$

Now assume that there is some element $(w^*, w) \in \Xi \setminus \mathcal{T}(\bar{y}, \bar{y}^*)^\circ$, i.e., there is some element $(v, v^*) \in \mathcal{T}(\bar{y}, \bar{y}^*)$ with $w^{*T}v + w^Tv^* > 0$. Then there are multipliers $\hat{\lambda} \in \hat{\Lambda}$, $\lambda \in \bar{\Lambda}(v)$ with $w^* \in -\nabla^2(\hat{\lambda}^T q)(\bar{y})w + \bar{K}^\circ$ and $v^* \in \nabla^2(\lambda^T q)(\bar{y})v + \hat{N}_{\bar{K}}(v)$ and hence

$$0 < w^{*^T} v + w^T v^* \le w^T \nabla^2 ((\lambda - \hat{\lambda})^T q) (\bar{y}) v.$$

Thus $v \neq 0$, $\bar{\Lambda}^{\mathcal{E}}(v) = \hat{\Lambda}$ and therefore $v^T \nabla^2 ((\lambda - \hat{\lambda})^T q)(\bar{y})v = 0$. For $\alpha > 0$ with $0 < 2w^T \nabla^2 ((\lambda - \hat{\lambda})^T q)(\bar{y})v + \alpha w^T \nabla^2 ((\lambda - \hat{\lambda})^T q)(\bar{y})w$ it follows that $0 < (v + \alpha w)^T \nabla^2 ((\lambda - \hat{\lambda})^T q)(\bar{y})(v + \alpha w)$ and hence $v + \alpha w \neq 0$ and $\hat{\lambda} \notin \bar{\Lambda}(v + \alpha w)$ contradicting $\hat{\lambda} \in \hat{\Lambda} = \bar{\Lambda}^{\mathcal{E}}(v + \alpha w) \subset \bar{\Lambda}(v + \alpha w)$. Hence $\Xi \subset \mathcal{T}(\bar{y}, \bar{y}^*)^\circ$ and equality in (27) is established.

To prove equality in the second case, note that $\bar{I}^+ = \overline{\mathcal{F}}$ implies $\bar{K} = \bar{\mathcal{N}}$ by Lemma 2. Consider now (w^*, w) belonging to the set on the right-hand side of (27) and an arbitrary element $(v, v^*) \in \mathcal{T}(\bar{y}, \bar{y}^*)$, i.e., $v \in \bar{\mathcal{N}}$ and $v^* \in \nabla^2(\lambda^T q(\bar{y}))w + \hat{N}_{\bar{K}}(v)$ for some $\lambda \in \bar{\Lambda}(v)$. Because of $v \in \bar{\mathcal{N}}$ we have $\hat{N}_{\bar{K}}(v) = \bar{K}^\circ$ and, by using the representation $w^* \in -\nabla^2(\bar{\lambda}^T q)(\bar{y})w + \bar{K}^\circ$ with $\bar{\lambda} \in \tilde{\Lambda}^{\mathcal{E}}(v)$, we obtain

$$w^{*T}v + w^Tv^* \le w^T \nabla^2 ((\lambda - \bar{\lambda})^T q)(\bar{y})v = 0$$

because of $w \in \overline{\mathcal{W}}(v)$. Hence $(w^*, w) \in \mathcal{T}(\overline{y}, \overline{y}^*)^\circ$ and equality in (27) follows. \Box

THEOREM 2. Assume that M is metrically subregular at $(\bar{y}, 0)$. Then

$$\hat{N}_{\mathrm{gph}\,\hat{N}_{\Gamma}}(\bar{y},\bar{y}^{*}) \subset \left\{ (w^{*},w) \middle| w \in \bigcap_{v \in \bar{\mathcal{N}}} \tilde{\mathcal{W}}(v), w^{*} \in \bigcap_{v \in \bar{\mathcal{N}}} \bar{L}(v;w) \right\}.$$

$$\tag{29}$$

Equality holds if, in addition, M is metrically regular in the vicinity of \bar{y} and either for any $0 \neq v_1, v_2 \in \bar{K}$ it holds $\bar{\Lambda}^{\&}(v_1) = \bar{\Lambda}^{\&}(v_2)$ or $\bar{I}^+ = \overline{\mathcal{F}}$.

PROOF. If *M* is metrically subregular, then by Gfrerer [6, Theorem 6.1(2.b)] one has that for every $v \in T_{\Gamma}^{\text{lin}}(\bar{y})$ we have $v^T \nabla^2 (\lambda^T q)(\bar{y}) v \leq 0$ for all λ belonging to the recession cone \mathcal{R} of $\bar{\Lambda}$. Hence, $\bar{\Lambda}(v) \neq \emptyset$, $\forall v \in T_{\Gamma}^{\text{lin}}(\bar{y}) \supset \bar{K}$ and the assertion of the theorem follows from Theorem 1 and Proposition 5. \Box

It follows from the definition of the regular coderivative that under metric subregularity of M at $(\bar{y}, 0)$ one has

$$\hat{D}^* \hat{N}_{\Gamma}(\bar{y}, \bar{y}^*)(w) \begin{cases} \subset \bigcap_{v \in \bar{\mathcal{N}}} \bar{L}(v; -w) & \text{if } w \in \bigcap_{v \in \bar{\mathcal{N}}} -\bar{\mathcal{W}}(v), \\ = \varnothing & \text{else.} \end{cases}$$
(30)

Equality holds in this formula provided M is metrically regular in the vicinity of \bar{y} and either for any $0 \neq v_1$, $v_2 \in \bar{K}$ it holds $\bar{\Lambda}^{\mathscr{C}}(v_1) = \bar{\Lambda}^{\mathscr{C}}(v_2)$ or $\bar{I}^+ = \overline{\mathcal{F}}$.

EXAMPLE 2. The normal cone mapping of the set

$$\Gamma := \left\{ y \in \mathbb{R}^3 \left| \begin{array}{c} y_1 + \frac{1}{2}y_2^2 \le 0 \\ y_1 + y_2^2 - y_2y_3 \le 0 \end{array} \right. \right\}$$

is given by

$$\hat{N}_{\Gamma}(y) = \begin{cases} \{(0,0,0)\} & \text{if } y_1 < -\max\left\{\frac{1}{2}y_2^2, y_2^2 - y_2y_3\right\}, \\ \{(\lambda_1,\lambda_1y_2,0) \mid \lambda_1 \ge 0\} & \text{if } y_1 = -\frac{1}{2}y_2^2 < -y_2^2 + y_2y_3, \\ \{(\lambda_2,\lambda_2(2y_2 - y_3), -\lambda_2y_2) \mid \lambda_2 \ge 0\} & \text{if } y_1 = -y_2^2 + y_2y_3 < -\frac{1}{2}y_2^2, \\ \{(\lambda_1 + \lambda_2, (2\lambda_1 + 3\lambda_2)y_3, -2\lambda_2y_3) \mid \lambda_1, \lambda_2 \ge 0\} & \text{if } y_1 = -y_2^2 + y_2y_3 = -\frac{1}{2}y_2^2, y_2 \ne 0, \\ \{(\lambda_1 + \lambda_2, -\lambda_2y_3, 0) \mid \lambda_1, \lambda_2 \ge 0\} & \text{if } y_1 = y_2 = 0, \\ \varnothing & \text{else.} \end{cases}$$

Note that MFCQ is fulfilled at every point $y \in \Gamma$. The tangent cone and the Fréchet normal cone to gph \hat{N}_{Γ} at $\bar{y} = (0, 0, 0), \ \bar{y}^* = (1, 0, 0)$ are given by

$$\begin{split} T_{\text{gph}\,\hat{N}_{\Gamma}}(\bar{y},\bar{y}^{*}) &= \left\{ ((0,v_{2},v_{3}),(v_{1}^{*},v_{2},0)) \mid (0 \leq v_{2} \leq 2v_{3}) \lor (0 \geq v_{2} \geq 2v_{3}) \right\} \\ &\cup \left\{ ((0,v_{2},v_{3}),(v_{1}^{*},2v_{2}-v_{3},-v_{2})) \mid (v_{2} \leq 0 \land 2v_{3} \geq v_{2}) \lor (v_{2} \geq 0 \land 2v_{3} \leq v_{2}) \right\} \\ &\cup \left\{ ((0,2v_{3},v_{3}),(v_{1}^{*},(2+\lambda_{2})v_{3},-2\lambda_{2}v_{3})) \mid 0 \leq \lambda_{2} \leq 1 \right\} \\ &\cup \left\{ ((0,0,v_{3}),(v_{1}^{*},-\lambda_{2}v_{3},0)) \mid 0 \leq \lambda_{2} \leq 1 \right\} \end{split}$$

and

$$\begin{split} \hat{N}_{\text{gph}\,\hat{N}_{\Gamma}}(\bar{y},\bar{y}^{*}) &= \left\{ ((w_{1}^{*},-w_{2},0),(0,w_{2},w_{3})) \right\} \\ &\cap \left\{ ((w_{1}^{*},w_{3}-2w_{2},w_{2}),(0,w_{2},w_{3})) \right\} \\ &\cap \left\{ ((w_{1}^{*},w_{2}^{*},w_{3}^{*}),(0,2w_{3},w_{3})) \mid 2w_{2}^{*}+w_{3}^{*}+4w_{3}=0 \right\} \\ &\cap \left\{ ((w_{1}^{*},w_{2}^{*},0),(0,0,w_{3})) \right\} \\ &= \left\{ ((w_{1}^{*},0,0),(0,0,0)) \right\}. \end{split}$$

Further we have $\bar{K} = \bar{\mathcal{N}} = \{0\} \times \mathbb{R} \times \mathbb{R}$, $\bar{\Lambda} = \{(\lambda_1, \lambda_2) \mid \lambda_1 \ge 0, \lambda_2 \ge 0, \lambda_1 + \lambda_2 = 1\}$ and for $v \in \bar{K}$ we obtain

$$\bar{\Lambda}(v) = \begin{cases} \{(1,0)\} & \text{if } v_2^2 > 2v_2v_3, \\ \bar{\Lambda} & \text{if } v_2 = 0 \text{ or } v_2 = 2v_3, \\ \{(0,1)\} & \text{if } v_2^2 < 2v_2v_3. \end{cases}$$

For $\tilde{v} := (0, 2, 1) \in \overline{\mathbb{N}}$, $\hat{v} := (0, 0, 1) \in \overline{\mathbb{N}}$ we have $\overline{\Lambda}(\tilde{v}) = \overline{\Lambda}(\hat{v}) = \overline{\Lambda}$ and for every $\lambda^1, \lambda^2 \in \overline{\Lambda}$ we obtain

$$w^{T}\nabla^{2}((\lambda^{1} - \lambda^{2})^{T}q)(\bar{y})\tilde{v} = w_{2}\tilde{v}_{2}(\lambda_{1}^{1} - \lambda_{1}^{2} + 2(\lambda_{2}^{1} - \lambda_{2}^{2})) - (w_{2}\tilde{v}_{3} + w_{3}\tilde{v}_{2})(\lambda_{2}^{1} - \lambda_{2}^{2})$$
$$= (\lambda_{2}^{1} - \lambda_{2}^{2})(w_{2}\tilde{v}_{2} - w_{2}\tilde{v}_{3} - w_{3}\tilde{v}_{2}) = (\lambda_{2}^{1} - \lambda_{2}^{2})(w_{2} - 2w_{3})$$

and, similarly,

$$w^T \nabla^2 ((\lambda^1 - \lambda^2)^T q)(\bar{y})\hat{v} = -(\lambda_2^1 - \lambda_2^2)w_2.$$

Thus $\bar{\mathcal{W}}(\tilde{v}) = \{(0, w_2, w_3) \mid w_2 = 2w_3\}, \ \bar{\mathcal{W}}(\hat{v}) = \{(0, 0, w_3)\} \text{ and } \bigcap_{v \in \bar{\mathcal{N}}} \bar{\mathcal{W}}(v) = \{(0, 0, 0)\}. \text{ Since for every } v \in \bar{\mathcal{N}} \text{ we have } \bar{\mathcal{V}}(v) = \bar{\mathcal{V$

$$L(v; 0) = K^{\circ} = \mathbb{R} \times \{0\} \times \{0\},\$$

we obtain

$$\left\{ (w^*, w) \middle| w \in \bigcap_{v \in \bar{\mathcal{N}}} \bar{\mathcal{W}}(v), w^* \in \bigcap_{v \in \bar{\mathcal{N}}} \bar{L}(v; w) \right\} = \bar{K}^{\circ} \times \{ (0, 0, 0) \} = \hat{N}_{\text{gph}\,\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$$

or $\hat{D}^*\hat{N}_{\Gamma}(\bar{y},\bar{y}^*)(0) = \bar{K}^\circ$, $\hat{D}^*\hat{N}_{\Gamma}(\bar{y},\bar{y}^*)(w) = \emptyset$, $w \neq 0$ and equality in (29) holds. \triangle

EXAMPLE 3. The normal cone mapping of the set

$$\Gamma := \left\{ y \in \mathbb{R}^3 \middle| \begin{array}{l} y_1 + \frac{1}{2}y_2^2 \le 0\\ y_1 + y_2^2 - y_2y_3 \le 0\\ y_2 \le 0 \end{array} \right\}$$

is given by

$$\hat{N}_{\Gamma}(y) = \begin{cases} \{(0, \lambda_3, 0) \mid \lambda_3 \ge 0\} & \text{if } y_1 < 0, \ y_2 = 0, \\ \{(\lambda_1 + \lambda_2, -\lambda_2 y_3 + \lambda_3, 0) \mid \lambda_1, \lambda_2, \lambda_3 \ge 0\} & \text{if } y_1 = y_2 = 0, \\ \{(\lambda_1, \lambda_1 y_2, 0) \mid \lambda_1 \ge 0\} & \text{if } 2y_3 < y_2 < 0, \ y_1 = -\frac{1}{2}y_2^2, \\ \{(\lambda_2, \lambda_2(2y_2 - y_3), -\lambda_2 y_2) \mid \lambda_2 \ge 0\} & \text{if } 2y_3 > y_2, \ y_2 < 0, \ y_1 = -\frac{1}{2}y_2^2, \\ \{(\lambda_1 + \lambda_2, (2\lambda_1 + 3\lambda_2)y_3, -2\lambda_2 y_3) \mid \lambda_1, \lambda_2 \ge 0\} & \text{if } 2y_3 = y_2 < 0, \ y_1 = -\frac{1}{2}y_2^2, \\ \{(0, 0, 0)\} & \text{if } y_2 < 0, \ y_1 < -\max\{\frac{1}{2}y_2^2, y_2^2 - y_2 y_3\}, \\ \varnothing & \text{else.} \end{cases}$$

The tangent cone and the Fréchet normal cone to gph \hat{N}_{Γ} at $\bar{y} = (0, 0, 0)$, $\bar{y}^* = (1, 0, 0)$ are given by

$$\begin{split} T_{\mathrm{gph}\,\hat{N}_{\Gamma}}(\bar{y},\bar{y}^{*}) &= \left\{ ((0,0,v_{3}),(v_{1}^{*},v_{2}^{*},0)) \mid v_{2}^{*} \geq \min\{-v_{3},0\} \right\} \\ &\cup \left\{ ((0,v_{2},v_{3}),(v_{1}^{*},v_{2},0)) \mid 2v_{3} \leq v_{2} \leq 0 \right\} \\ &\cup \left\{ ((0,v_{2},v_{3}),(v_{1}^{*},2v_{2}-v_{3},-v_{2})) \mid 2v_{3} \geq v_{2},v_{2} \leq 0 \right\} \\ &\cup \left\{ ((0,2v_{3},v_{3}),(v_{1}^{*},(2+\lambda_{2})v_{3},-2\lambda_{2}v_{3})) \mid v_{3} \leq 0, 0 \leq \lambda_{2} \leq 1 \right\} \end{split}$$

and

$$\begin{split} \hat{N}_{\mathrm{gph}\,\hat{N}_{\Gamma}}(\bar{y},\bar{y}^{*}) &= \left\{ ((w_{1}^{*},w_{2}^{*},w_{3}^{*}),(0,w_{2},w_{3})) \mid w_{2} \leq w_{3}^{*} \leq 0 \right\} \\ &\cap \left\{ ((w_{1}^{*},w_{2}^{*},w_{3}^{*}),(0,w_{2},w_{3})) \mid w_{2}^{*} + \frac{1}{2}w_{3}^{*} + w_{2} \geq 0, w_{3}^{*} \geq 0 \right\} \\ &\cap \left\{ ((w_{1}^{*},w_{2}^{*},w_{3}^{*}),(0,w_{2},w_{3})) \mid w_{2} - w_{3}^{*} \geq 0, w_{2}^{*} + \frac{3}{2}w_{2} + \frac{1}{2}w_{3}^{*} - w_{3} \geq 0 \right\} \\ &\cap \left\{ ((w_{1}^{*},w_{2}^{*},w_{3}^{*}),(0,w_{2},w_{3})) \mid 2w_{2}^{*} + w_{3}^{*} + 2w_{2} + \min\{w_{2} - 2w_{3},0\} \geq 0 \right\} \\ &= \left\{ ((w_{1}^{*},w_{2}^{*},0),(0,0,w_{3})) \mid w_{2}^{*} \geq \max\{w_{3},0\} \right\}. \end{split}$$

Then $\bar{K} = \{0\} \times \mathbb{R}_{-} \times \mathbb{R}, \ \bar{\mathcal{N}} = \{0\} \times \{0\} \times \mathbb{R}, \ \bar{\Lambda} = \{(\lambda_1, \lambda_2, 0) \mid \lambda_1 \ge 0, \lambda_2 \ge 0, \lambda_1 + \lambda_2 = 1\}$ and for $v \in \bar{K}$ we have

$$\bar{\Lambda}(v) = \begin{cases} \{(1,0,0)\} & \text{if } 0 > v_2 > 2v_3, \\ \bar{\Lambda} & \text{if } v_2 = 0 \text{ or } 0 > v_2 = 2v_3, \\ \{(0,1,0)\} & \text{if } v_2 < 2v_3 \text{ and } v_2 < 0. \end{cases}$$

For every $0 \neq v = (0, 0, v_3) \in \overline{\mathcal{N}}$ we obtain

$$\tilde{\mathcal{W}}(v) = \left\{ w \in \bar{K} \mid w^T \nabla^2 ((\lambda^1 - \lambda^2)^T q) (\bar{y}) v = w_2 (\lambda_2^2 - \lambda_2^1) v_3 = 0, \ \forall \lambda^1, \lambda^2 \in \bar{\Lambda}(v) = \bar{\Lambda} \right\} = \{0\} \times \{0\} \times \mathbb{R},$$
$$\tilde{\Lambda}^{\mathcal{E}}(v) = \bar{\Lambda}^{\mathcal{E}}(v) = \bar{\Lambda}$$

and for $w \in \bar{\mathcal{W}}(v)$

$$\bar{L}(v;w) = \{(0,\lambda_2w_3,0) \mid 0 \le \lambda_2 \le 1\} + \bar{K}^\circ = \mathbb{R} \times [\min\{w_3,0\},\infty) \times \{0\}$$

Hence

$$\begin{cases} (w^*, w) \mid w \in \bigcap_{v \in \bar{\mathcal{N}}} \bar{\mathcal{W}}(v), w^* \in \bigcap_{v \in \bar{\mathcal{N}}} \bar{L}(v; w) \end{cases} = \{ ((w_1^*, w_2^*, 0), (0, 0, w_3)) \mid w_2^* \ge \min\{w_3, 0\} \} \\ \neq \{ ((w_1^*, w_2^*, 0), (0, 0, w_3)) \mid w_2^* \ge \max\{w_3, 0\} \} \\ = \hat{N}_{\text{sph}} \hat{y}_{\text{c}}(\bar{y}, \bar{y}^*) \end{cases}$$

yielding

$$\hat{D}^* \hat{N}_{\Gamma}(\bar{y}, \bar{y}^*)(w) \begin{cases} \subset \{(w_1^*, w_2^*, 0) \mid w_2^* \ge \min\{-w_3, 0\}\} & \text{if } w_1 = w_2 = 0 \\ = \varnothing & \text{else} \end{cases}$$

and equality does not hold. \triangle

In the case when the set $\overline{\Lambda}(v)$ remains constant for all $0 \neq v \in \overline{K}$, the formulas for the contingent cone and the regular normal cone of gph \hat{N}_{Γ} can be simplified considerably.

LEMMA 4. Assume that $\bar{\Lambda}(v_1) = \bar{\Lambda}(v_2), \forall 0 \neq v_1, v_2 \in \bar{K}$. Then for all $v \in \bar{K}$ and all $\lambda^1, \lambda^2 \in \bar{\Lambda}(v)$ we have $\nabla^2((\lambda^1 - \lambda^2)^T q)(\bar{y})v \in \operatorname{span}\{\nabla q_i(\bar{y})^T \mid i \in \bar{I}^+\}.$

PROOF BY CONTRAPOSITION. Assume on the contrary that there are $v \in \overline{K}$ and $\lambda^1, \lambda^2 \in \overline{\Lambda}(v)$ such that $\nabla^2((\lambda^1 - \lambda^2)^T q)(\overline{y})v \notin \operatorname{span}\{\nabla q_i(\overline{y})^T \mid i \in \overline{I}^+\}$. This is equivalent with the existence of some w satisfying $\nabla q_i(\overline{y})w = 0$, $i \in \overline{I}^+$, and $w^T \nabla^2((\lambda^1 - \lambda^2)^T q)(\overline{y})v \neq 0$. By Lemma 2 there is some \widetilde{v} with

$$\nabla q_i(\bar{y})\tilde{v} \begin{cases} = 0 & i \in \bar{I}^+, \\ < 0 & i \in \bar{I}^0 \end{cases}$$

and hence $w + \alpha \tilde{v} \in \bar{K}$ for all α sufficiently large. Moreover, we can choose the value of α such that, in addition, $\tilde{w}^T \nabla^2 ((\lambda^1 - \lambda^2)^T q)(\bar{y}) v \neq 0$, where $\tilde{w} = w + \alpha \tilde{v}$. We can assume without loss of generality that $\tilde{w}^T \nabla^2 ((\lambda^1 - \lambda^2)^T q)(\bar{y}) v < 0$, because otherwise we can interchange λ^1 and λ^2 . Then we can choose the value of $\beta > 0$ with $v + \beta \tilde{w} \neq 0$ and $\tilde{w}^T \nabla^2 ((\lambda^1 - \lambda^2)^T q)(\bar{y})(2v + \beta \tilde{w}) < 0$. It follows $v + \beta \tilde{w} \in \bar{K}$ and, together with $v^T \nabla^2 ((\lambda^1 - \lambda^2)^T q)(\bar{y})v = 0$ because of $\lambda^1, \lambda^2 \in \bar{\Lambda}(v)$,

$$(v+\beta\tilde{w})^T\nabla^2((\lambda^1-\lambda^2)^Tq)(\bar{y})(v+\beta\tilde{w}) = \beta\tilde{w}^T\nabla^2((\lambda^1-\lambda^2)^Tq)(\bar{y})(2v+\beta\tilde{w}) < 0$$

showing $\lambda^1 \notin \overline{\Lambda}(v + \beta \tilde{w})$. Therefore $\overline{\Lambda}(v + \beta \tilde{w}) \neq \overline{\Lambda}(v)$, a contradiction, since we also have $v \neq 0$. \Box

Note that the condition $\bar{\Lambda}(v_1) = \bar{\Lambda}(v_2)$, $\forall 0 \neq v_1, v_2 \in \bar{K}$ implies in particular the corresponding property for the sets $\bar{\Lambda}^{\mathcal{E}}$ used in Theorem 2.

THEOREM 3. Assume that M is metrically subregular at $(\bar{y}, 0)$ and metrically regular in the vicinity of \bar{y} . Further assume that $\bar{\Lambda}(v_1) = \bar{\Lambda}(v_2)$, $\forall 0 \neq v_1, v_2 \in \bar{K}$ and let $\bar{\lambda}$ be an arbitrary multiplier from $\bar{\Lambda}(v)$ for some $0 \neq v \in \bar{K}$, if $\bar{K} \neq \{0\}$ and $\bar{\lambda} \in \bar{\Lambda}$ otherwise. Then

$$T_{\text{gph}\,\hat{N}_{\Gamma}}(\bar{y},\bar{y}^{*}) = \{(v,v^{*}) \mid v^{*} \in \nabla^{2}(\bar{\lambda}^{T}q)(\bar{y})v + \hat{N}_{\bar{K}}(v)\}$$
(31)

and

$$\hat{N}_{\text{gph}\,\hat{N}_{\Gamma}}(\bar{y},\bar{y}^{*}) = \{(w^{*},w) \mid w \in \bar{K}, w^{*} \in -\nabla^{2}(\bar{\lambda}^{T}q)(\bar{y})w + \bar{K}^{\circ}\}.$$
(32)

Consequently,

$$D\hat{N}_{\Gamma}(\bar{y}, \bar{y}^{*})(v) = \nabla^{2}(\bar{\lambda}^{T}q)(\bar{y})v + \hat{N}_{\bar{K}}(v), \quad v \in \mathbb{R}^{m},$$
$$\hat{D}^{*}\hat{N}_{\Gamma}(\bar{y}, \bar{y}^{*})(w) = \begin{cases} \nabla^{2}(\bar{\lambda}^{T}q)(\bar{y})w + \bar{K}^{\circ} & if - w \in \bar{K}, \\ \varnothing & else. \end{cases}$$

PROOF. By Theorem 1 it is clear that the set on the right-hand side of (31) is contained in $T_{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$. To show the reverse inclusion, fix any $(v, v^*) \in T_{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$. Then there is some $\lambda \in \bar{\Lambda}(v)$ with $v^* \in \nabla^2(\lambda^T q)(\bar{y})v + \hat{N}_{\bar{K}}(v)$ and by Lemma 4 together with the identity span $\{\nabla q_i(\bar{y})^T \mid i \in \bar{I}^+\} + \hat{N}_{\bar{K}}(v) = \hat{N}_{\bar{K}}(v)$ we obtain $v^* \in \nabla^2(\bar{\lambda}^T q)(\bar{y})v + \sin\{\nabla q_i(\bar{y})^T \mid i \in \bar{I}^+\} + \hat{N}_{\bar{K}}(v) = \nabla^2(\bar{\lambda}^T q)(\bar{y})v + \hat{N}_{\bar{K}}(v)$, showing the desired inclusion.

To show (32), note that by our assumptions equality holds in (29). Further, by Lemmas 4 and 2 we obtain $\bar{\mathcal{W}}(v) = \bar{K}, \forall v \in \bar{\mathcal{N}}$ and, by using the same arguments as above, $L(v; w) = -\nabla^2(\bar{\lambda}^T q)(\bar{y})w + \bar{K}^\circ, \forall w \in \bar{K}$. Equality (32) follows now from Theorem 2. \Box

The behavior of the mapping $\overline{\Lambda}$ required in the above theorem is automatically fulfilled whenever MFCQ and CRCQ¹ hold at \overline{y} ; see Henrion et al. [10, Corollary 3.2, Remark 3.1]. The following example shows, however, that the requirements of the theorem can very well be satisfied even without CRCQ.

EXAMPLE 4. Let $\Gamma \subset \mathbb{R}^2$ be given by

$$q(y) = \begin{pmatrix} -y_1^2 + y_2 \\ -y_1^2 - y_2 \\ y_1 \end{pmatrix}.$$

Put $\bar{y} = 0$, $\bar{y}^* = 0$ and let us compute $T_{gph \hat{N}_{\Gamma}}(0, 0)$. It follows that

$$\bar{K} = T_{\Gamma}(0) = \{v | v_1 \le 0, v_2 = 0\},$$
$$\bar{\Lambda} = \{\lambda \in \mathbb{R}^3_+ \mid \lambda_1 = \lambda_2, \lambda_3 = 0\},$$

and

$$\bar{\Lambda}(v) = \begin{cases} \{\lambda \in \bar{\Lambda} \mid \lambda_1 + \lambda_2 = 0\} = \{0\} & \text{if } 0 \neq v \in \bar{K}, \\ \bar{\Lambda} & \text{if } v = 0. \end{cases}$$

It is easy to show that the second-order sufficient conditions for metric subregularity SOSCMS from Proposition 2 are fulfilled and thus M is metrically subregular and even metrically regular in the vicinity of 0 by Proposition 3. It follows that we can compute $T_{\text{gph}\hat{N}_{r}}(0,0)$ according to Theorem 3 and obtain

$$T_{gph\,\hat{N}_{\Gamma}}(0,0) = \{(v,v^*) \mid v^* \in \hat{N}_{\bar{K}}(v)\},\$$

and, since $\bar{K}^{\circ} = \hat{N}_{\Gamma}(0) = \mathbb{R}_{+} \times \mathbb{R}$, one has

$$T_{\mathrm{gph}\,\hat{N}_{\Gamma}}(0,0) = \left(\{v \mid v_1 \le 0, v_2 = 0\} \times \{v^* \mid v_1^* = 0\}\right) \cup \left(\{0,0\} \times \mathbb{R}_+ \times \mathbb{R}\right)$$

Consequently,

$$\hat{N}_{\text{gph}\,\hat{N}_{\Gamma}}(0,0) = (T_{\text{gph}\,\hat{N}_{\Gamma}}(0,0))^{\circ} = \{(v_{1}^{*},v_{2}^{*}) \mid v_{1}^{*} \ge 0\} \times \{(v_{1},0) \mid v_{1} \le 0\} = (\bar{K})^{\circ} \times \bar{K}$$

verifying (32) with $\bar{\lambda} = 0$. \triangle

5. Regular coderivative of the solution map. In the preceding section, we have computed (an upper estimate of) the regular coderivative of \hat{N}_{Γ} . To compute the regular coderivative of S we need, in addition, a chain rule for regular normal cones without any convexity assumptions. Such a chain rule is provided in the next statement, which is important for its own sake and can be used also in completely different situations.

THEOREM 4. Let

$$\Omega := \{ x \in \mathbb{R}^n \mid G(x) \in D \}$$

for a closed set $D \subset \mathbb{R}^m$ and a mapping $G: \mathbb{R}^n \to \mathbb{R}^m$ continuously differentiable near $\bar{x} \in \Omega$. If the multifunction $x \Rightarrow G(x) - D$ is metrically subregular at $(\bar{x}, 0)$ and there exists a subspace $L \subset \mathbb{R}^m$ such that

$$T_D(G(\bar{x})) + L \subset T_D(G(\bar{x})) \tag{33}$$

and

$$\nabla G(\bar{x})\mathbb{R}^n + L = \mathbb{R}^m,\tag{34}$$

¹ One says that Γ fulfills CRCQ at \bar{y} provided there exists a neighborhood \mathcal{M} of \bar{y} such that for any subsets I of \mathcal{F} , the family of gradients $\{\nabla q_i(y) \mid i \in I\}$ has the same rank for all $y \in \mathcal{M}$.

then

$$\hat{N}_{\Omega}(\bar{x}) = \nabla G(\bar{x})^T \hat{N}_D(G(\bar{x})).$$

PROOF. The inclusion $\hat{N}_{\Omega}(\bar{x}) \supset \nabla G(\bar{x})^T \hat{N}_D(G(\bar{x})$ follows immediately from Rockafellar and Wets [26, Theorem 6.14]. To show the reverse inclusion, let $x^* \in \hat{N}_{\Omega}(\bar{x})$ and consider $h \in \mathcal{S} := \{h \in \mathbb{R}^n \mid \nabla G(\bar{x})h \in \text{conv } T_D(G(\bar{x}))\}$. Then $\nabla G(\bar{x})h$ can be written as convex combination of elements of $T_D(G(\bar{x}))$:

$$\nabla G(\bar{x})h = \sum_{i=1}^{N} \alpha_i t_i, \quad t_i \in T_D(G(\bar{x})), \quad \alpha_i \ge 0, \quad i = 1, \dots, N; \qquad \sum_{i=1}^{N} \alpha_i = 1$$

By the assumptions of the theorem, each of the tangents t_i can be represented as $t_i = \nabla G(\bar{x})h_i + l_i$, where $h_i \in \mathbb{R}^n$ and $l_i \in L$. Since *L* is a subspace we also have $-l_i \in L$ showing $\nabla G(\bar{x})h_i = t_i - l_i \in T_D(G(\bar{x})) + L \subset T_D(G(\bar{x}))$. Because $G(\cdot) - D$ is assumed to be metrically subregular at $(\bar{x}, 0)$, it follows from Henrion and Outrata [9, Proposition 1] that

$$T_{\Omega}(\bar{x}) = \{ u \mid \nabla G(\bar{x})u \in T_D(G(\bar{x})) \}.$$
(35)

Hence, we conclude $h_i \in T_{\Omega}(\bar{x})$ and $\langle x^*, h_i \rangle \leq 0$. Further we have

$$\nabla G(\bar{x})\left(h-\sum_{i=1}^{N}\alpha_{i}h_{i}\right)=\sum_{i=1}^{N}\alpha_{i}(t_{i}-\nabla G(\bar{x})h_{i})=\sum_{i=1}^{N}\alpha_{i}l_{i}\in L\subset T_{D}(G(\bar{x})),$$

and, again by (35), we obtain $h - \sum_{i=1}^{N} \alpha_i h_i \in T_{\Omega}(\bar{x})$. Thus $\langle x^*, h - \sum_{i=1}^{N} \alpha_i h_i \rangle \leq 0$ implying

$$\langle x^*, h \rangle \leq \left\langle x^*, \sum_{i=1}^N \alpha_i h_i \right\rangle = \sum_{i=1}^N \alpha_i \langle x^*, h_i \rangle \leq 0.$$

From this it follows that $x^* \in \mathscr{S}^\circ$ and, by Rockafellar [25, Corollary 16.3.2], we can conclude $\hat{N}_{\Omega}(\bar{x}) \subset \mathscr{S}^\circ = \nabla G(\bar{x})^T (\operatorname{conv} T_D(G(\bar{x})))^\circ = \nabla G(\bar{x})^T \hat{N}_D(G(\bar{x}))$, provided there exists some u with $\nabla G(\bar{x})u \in \operatorname{ri conv} T_D(G(\bar{x}))$. To show the existence of such an element u, choose any $t \in \operatorname{ri conv} T_D(G(\bar{x}))$ and select u and $l \in L$ such that $\nabla G(\bar{x})u + l = t$. Since we also have $\operatorname{conv} T_D(\bar{x}) + L \subset \operatorname{conv} T_D(\bar{x})$, we obtain from Rockafellar [25, Theorem 6.1] that $\nabla G(\bar{x})u = \frac{1}{2}(t-2l) + \frac{1}{2}t \in \operatorname{ri conv} T_D(G(\bar{x}))$. Hence $\hat{N}_{\Omega}(\bar{x}) \subset \nabla G(\bar{x})^T \hat{N}_D(G(\bar{x}))$ holds and this completes the proof. \Box

If D is convex, then the conditions (33), (34) amount to

$$\nabla G(\bar{x})\mathbb{R}^n + \lim T_D(G(\bar{x})) = \mathbb{R}^m, \tag{36}$$

where lin stands for the lineality space. This condition is known as nondegeneracy Bonnans and Shapiro [2, Definition 4.70]. In the nonconvex case, however, the formulation (36) cannot be used because of (33).

Consider now the mapping $\tilde{S}: \mathbb{R}^n \rightrightarrows \mathbb{R}^m$ defined by

$$\tilde{S}(x) = \begin{cases} \{y \in \mathbb{R}^m \mid 0 \in F(x, y) + \hat{N}_{\Gamma}(y)\} & \text{if } x \in C, \\ \varnothing & \text{otherwise,} \end{cases}$$

where $F: \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}^m$ is continuously differentiable and $C \subset \mathbb{R}^n$ is a closed set.

Associated with \tilde{S} is the perturbation mapping $\Psi \colon \mathbb{R}^n \times \mathbb{R}^m \rightrightarrows (\mathbb{R}^m \times \mathbb{R}^m) \times \mathbb{R}^n$ given by

$$\Psi(x,y) := G(x,y) - D, \qquad G(x,y) := \begin{pmatrix} (y, -F(x,y)) \\ x \end{pmatrix}, \quad D := \operatorname{gph} \hat{N}_{\Gamma} \times C, \tag{37}$$

so that $gph \tilde{S} = \{(x, y) \mid 0 \in \Psi(x, y)\}.$

THEOREM 5. Consider $(\bar{x}, \bar{y}) \in \text{gph } \hat{S}$. Assume that M is metrically subregular at $(\bar{y}, 0)$ and metrically regular in the vicinity of \bar{y} . Further assume that the set-valued mapping Ψ given by (37) is metrically subregular at $((\bar{x}, \bar{y})), (0, 0, 0))$, and suppose that there exists a subspace $P \subset T_C(\bar{x})$ with $T_C(\bar{x}) + P \subset T_C(\bar{x})$ and

$$\nabla_{x}F(\bar{x},\bar{y})P + \operatorname{span}\{\nabla q_{i}(\bar{y})^{T} \mid i \in \bar{I}^{+}\} = \mathbb{R}^{m}.$$
(38)

Then one has, with $\bar{y}^* := -F(\bar{x}, \bar{y})$, that

$$\hat{N}_{gph\,\tilde{S}}(\bar{x},\bar{y}) = \nabla G(\bar{x},\bar{y})^T \hat{N}_D(G(\bar{x},\bar{y}))
= \left\{ \begin{pmatrix} -\nabla_x F(\bar{x},\bar{y})^T w + c^* \\ -\nabla_y F(\bar{x},\bar{y})^T w + w^* \end{pmatrix} \middle| c^* \in \hat{N}_C(\bar{x}), \ (w^*,w) \in \hat{N}_{gph\,\hat{N}_{\Gamma}}(\bar{y},\bar{y}^*) \right\}.$$
(39)

PROOF. Set $\Omega := \{(x, y) \mid G(x, y) \in D\} = \operatorname{gph} \tilde{S}$. We will invoke Theorem 4 to prove that $\hat{N}_{\Omega}(\bar{x}, \bar{y}) = \nabla G(\bar{x}, \bar{y})^T \hat{N}_D(G(\bar{x}, \bar{y}))$. Using Lemmas 1, 2 we obtain $\tilde{L} := \operatorname{span}\{\nabla q_i(\bar{y})^T \mid i \in \bar{I}^+\} \subset \hat{N}_{\bar{K}}(v), \forall v \in \bar{K}$. Hence $T_{\operatorname{gph} \hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*) + \{0_m\} \times \tilde{L} \subset T_{\operatorname{gph} \hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$ by virtue of Theorem 1. Defining the subspace L by $L := (\{0_m\} \times \tilde{L}) \times P$ and taking into account $T_D(G(\bar{x}, \bar{y})) = T_{\operatorname{gph} \hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*) \times T_C(\bar{x})$, we obtain $T_D(G(\bar{x}, \bar{y})) + L \subset T_D(G(\bar{x}, \bar{y}))$. Next, we shall prove that

$$\nabla G(\bar{x}, \bar{y})(\mathbb{R}^n \times \mathbb{R}^m) + L = (\mathbb{R}^m \times \mathbb{R}^m) \times \mathbb{R}^n \tag{40}$$

holds true. By the assumptions for any $((v, v^*), u) \in (\mathbb{R}^m \times \mathbb{R}^m) \times \mathbb{R}^n$ we can choose $p \in P$ and $\tilde{l} \in \tilde{L}$ with $\nabla_x F(\bar{x}, \bar{y})p + \tilde{l} = v^* + \nabla_x F(\bar{x}, \bar{y})u + \nabla_y F(\bar{x}, \bar{y})v$. Then $l = ((0_m, \tilde{l}), p) \in L$ and

$$\nabla G(\bar{x}, \bar{y}) \begin{pmatrix} u-p\\v \end{pmatrix} + l = \begin{pmatrix} (v, -\nabla_x F(\bar{x}, \bar{y})(u-p) - \nabla_y F(\bar{x}, \bar{y})v + \tilde{l})\\u-p+p \end{pmatrix} = \begin{pmatrix} (v, v^*)\\u \end{pmatrix}.$$

This verifies (40) and we can apply Theorem 4 to obtain the result. \Box

COROLLARY 1. In the setting of Theorem 5 for any $v^* \in \mathbb{R}^m$ one has

$$\hat{D}^* \tilde{S}(\bar{x}, \bar{y})(v^*) = \left\{ \nabla_x F(\bar{x}, \bar{y})^T w + \hat{N}_C(\bar{x}) \mid 0 \in v^* + \nabla_y F(\bar{x}, \bar{y})^T w + \hat{D}^* \hat{N}_\Gamma(\bar{y}, \bar{y}^*)(w) \right\}.$$
(41)

There are various possibilities for verifying the metric subregularity of Ψ at $((\bar{x}, \bar{y}), (0, 0, 0))$. Sometimes one can use even the following simple sufficient condition for metric regularity stated in Proposition 6. We think that this criterion is far away from being necessary, but it is easy to verify.

PROPOSITION 6. Let Ψ be given by (37), and let $0 \in \Psi(\bar{x}, \bar{y})$. Assume that M is metrically subregular at $(\bar{y}, 0)$ and metrically regular in the vicinity of \bar{y} . Further assume that for every $\lambda \in \mathcal{E}$, the set of extreme points of $\Lambda(\bar{y}, -F(\bar{x}, \bar{y}))$, one has

$$\left. \begin{array}{l} \nabla_{x}F(\bar{x},\bar{y})^{T}v \in N_{C}(\bar{x}),\\ \nabla q_{i}(\bar{x})v = 0, \ i \in I^{+}(\lambda) \end{array} \right\} \Rightarrow v = 0.$$

Then Ψ is metrically regular near $((\bar{x}, \bar{y}), (0, 0, 0))$.

PROOF. By contraposition. Assuming now on the contrary that Ψ is not metrically regular near $((\bar{x}, \bar{y}), (0, 0, 0))$, by Rockafellar and Wets [26, Example 9.44] there is some nonzero $\xi = ((v^*, v), x^*) \in N_D(G(\bar{x}, \bar{y}))$ such that

$$\nabla G(\bar{x}, \bar{y})^T \xi = \begin{pmatrix} -\nabla_x F(\bar{x}, \bar{y})^T v + x^* \\ -\nabla_y F(\bar{x}, \bar{y})^T v + v^* \end{pmatrix} = 0,$$

$$(42)$$

where G and D are given by (37). It can be easily seen from (42) that $v \neq 0$ since otherwise $\xi = ((v^*, v), x^*)$ would be 0. By Rockafellar and Wets [26, Proposition 6.41] we have $N_D(G(\bar{x}, \bar{y})) = N_{\text{gph}\,\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*) \times N_C(\bar{x})$ with $\bar{y}^* := -F(\bar{x}, \bar{y})$, implying $\nabla_x F(\bar{x}, \bar{y})^T v = x^* \in N_C(\bar{x})$ and we will now show the existence of some $\lambda \in \mathcal{C}$ satisfying $\nabla q_i(\bar{y})v = 0$, $i \in I^+(\lambda)$, contradicting the assumption of the proposition.

Since $(v^*, v) \in N_{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$, there are sequences $(y_k, y_k^*) \xrightarrow{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$ and $(v_k^*, v_k) \to (v^*, v)$ with $(v_k^*, v_k) \in \hat{N}_{\text{gph}\hat{N}_{\Gamma}}(y_k, y_k^*)$. For every $(y, y^*) \in \text{gph}\hat{N}_{\Gamma}$ near (\bar{y}, \bar{y}^*) we have that M is at least metrically subregular at (y, 0). Thus, by Theorem 1 the cone $\{0_m\} \times K(y, y^*)^\circ$ is a subset of $T_{\text{gph}\hat{N}_{\Gamma}}(y, y^*)$ and this implies

$$(v_{k}^{*}, v_{k}) \in \hat{N}_{gph\,\hat{N}_{\Gamma}}(y_{k}, y_{k}^{*}) = (T_{gph\,\hat{N}_{\Gamma}}(y_{k}, y_{k}^{*}))^{\circ} \subset (\{0_{m}\} \times K(y_{k}, y_{k}^{*})^{\circ})^{\circ} = \mathbb{R}^{m} \times K(y_{k}, y_{k}^{*})$$

for all k sufficiently large. Using similar arguments as in the second part of the proof of Theorem 1, where we showed equality in (17), we can find a bounded sequence $(\lambda^k) \in \Lambda(y_k, y_k^*)$ and, by passing to a subsequence if necessary, we can assume that it converges to some $\tilde{\lambda} \in \bar{\Lambda}$. However, $\bar{\Lambda}$ is the sum of the convex hull of its extreme points and its recession cone and therefore there is some $\lambda \in \mathcal{C}$ with $I^+(\lambda) \subset I^+(\bar{\lambda})$. Then $I^+(\lambda) \subset I^+(\lambda^k)$ for all k sufficiently large and from $v_k \in K(y_k, y_k^*)$ we deduce $\nabla q_i(y_k)v_k = 0$, $i \in I^+(\lambda^k)$. Hence, by passing to the limit we obtain the claimed contradiction $\nabla q_i(\bar{y})v = 0$, $i \in I^+(\lambda)$, and the proposition is proved. \Box

The assumption (38) can be considerably weakened, if we strengthen our assumptions imposed on $\Lambda(\cdot)$. To simplify the formulas in the following theorem it is reasonable to introduce the Lagrangian associated with our generalized equation, i.e.,

$$\mathscr{L}(x, y, \lambda) = F(x, y) + \nabla q(y)^T \lambda.$$

THEOREM 6. Let $(\bar{x}, \bar{y}) \in \text{gph} \tilde{S}$ and assume that M is metrically subregular at $(\bar{y}, 0)$ and metrically regular in the vicinity of \bar{y} . Further assume that the set-valued mapping Ψ given by (37) is metrically subregular at $((\bar{x}, \bar{y})), (0, 0, 0))$, that $\bar{\Lambda}(v_1) = \bar{\Lambda}(v_2), \forall 0 \neq v_1, v_2 \in \bar{K}$ and suppose that there exists a subspace $P \subset T_C(\bar{x})$ with $T_C(\bar{x}) + P \subset T_C(\bar{x})$ and

$$\nabla_{x}F(\bar{x},\bar{y})P + \nabla_{y}\mathscr{L}(\bar{x},\bar{y},\bar{\lambda})\bar{\mathscr{N}} + \operatorname{span}\{\nabla q_{i}(\bar{y})^{T} \mid i \in \bar{I}^{+}\} = \mathbb{R}^{m},$$
(43)

where $\bar{\lambda} \in \bar{\Lambda}(v)$ for some $0 \neq v \in \bar{N}$ is chosen arbitrary, if $\bar{N} \neq \{0\}$, and $\bar{\lambda} = 0$ otherwise. Then (39) holds true and simplifies to

$$\hat{N}_{\mathrm{gph}\,\tilde{S}}(\bar{x},\bar{y}) = \left\{ \begin{pmatrix} -\nabla_{x}F(\bar{x},\bar{y})^{T}w\\ -\nabla_{y}\mathscr{L}(\bar{x},\bar{y},\bar{\lambda})w \end{pmatrix} \middle| w \in \bar{K} \right\} + \hat{N}_{C}(\bar{x}) \times \bar{K}^{\circ},$$
(44)

where \bar{K}, \bar{K}° are computed with $\bar{y}^* := -F(\bar{x}, \bar{y})$. Moreover, for any $v^* \in \mathbb{R}^m$ one has

$$\hat{D}^* \tilde{S}(\bar{x}, \bar{y})(v^*) = \left\{ \nabla_{\!x} F(\bar{x}, \bar{y})^T w + \hat{N}_C(\bar{x}) \mid 0 \in v^* + \nabla_{\!y} \mathscr{L}(\bar{x}, \bar{y}, \bar{\lambda}) w + \bar{K}^\circ, -w \in \bar{K} \right\}.$$

$$\tag{45}$$

PROOF. The proof follows the same lines as the proof of Theorem 5 with the exception that we choose now $L = \hat{L} \times P$, where $\hat{L} = \{(w, \nabla^2(\bar{\lambda}^T q)(\bar{y})w) \mid w \in \bar{\mathcal{N}}\} + \{0_m\} \times \tilde{L}$. To prove $T_{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*) + \hat{L} \subset T_{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$, choose any $(v, v^*) \in T_{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^*)$, $w \in \bar{\mathcal{N}}$ and $\xi \in \tilde{L}$. By Theorem 1 we have $v \in \bar{K}$ and there is some $\lambda \in \bar{\Lambda}(v)$ such that $v^* \in \nabla^2(\lambda^T q)(\bar{y})v + \hat{N}_{\bar{K}}(v)$. By Lemma 4 we have $\nabla^2(\lambda^T q)(\bar{y})v \in \nabla^2(\bar{\lambda}^T q)(\bar{y})v + \tilde{L}$. Since $\hat{N}_{\bar{K}}(v) + \tilde{L} = \hat{N}_{\bar{K}}(v)$ because of $\tilde{L} \subset \hat{N}_{\bar{K}}(v)$, since $\nabla q(\bar{y})w = 0$ because of $w \in \bar{\mathcal{N}}$ and since

$$\hat{N}_{\bar{K}}(v) = \{ \nabla q(\bar{y})^T \mu \mid \mu^T \nabla q(\bar{y})v = 0, \mu \in T_{\hat{N}_{\mathbb{R}^L}(q(\bar{y}))}(\lambda) \}$$

= $\{ \nabla q(\bar{y})^T \mu \mid \mu^T \nabla q(\bar{y})(v+w) = 0, \mu \in T_{\hat{N}_{\mathbb{R}^L}(q(\bar{y}))}(\lambda) \} = \hat{N}_{\bar{K}}(v+w)$

by virtue of Lemma 1, we obtain that

$$(v, v^*) + (w, \nabla^2(\bar{\lambda}^T q)(\bar{y})w) + (0_m, \xi) \in (v + w, \nabla^2(\bar{\lambda}^T q)(\bar{y})(v + w)) + \{0_m\} \times \hat{N}_{\bar{K}}(v + w).$$

This, together with $v + w \in \overline{K}$, shows the desired inclusion. To show (40), fix any $((v, v^*), u) \in (\mathbb{R}^m \times \mathbb{R}^m) \times \mathbb{R}^n$ and choose $p \in P$, $w \in \overline{N}$ and $\tilde{l} \in \tilde{L}$ with

$$\nabla_{\mathbf{x}}F(\bar{\mathbf{x}},\bar{\mathbf{y}})p + (\nabla_{\mathbf{y}}F(\bar{\mathbf{x}},\bar{\mathbf{y}}) + \nabla^2(\bar{\lambda}^T q)(\bar{\mathbf{y}}))w + \tilde{l} = v^* + \nabla_{\mathbf{x}}F(\bar{\mathbf{x}},\bar{\mathbf{y}})u + \nabla_{\mathbf{y}}F(\bar{\mathbf{x}},\bar{\mathbf{y}})v.$$

Then $l = ((w, \nabla^2(\bar{\lambda}^T q)(\bar{y}))w + \tilde{l}), p) \in L$ and

$$\begin{aligned} \nabla G(\bar{x}, \bar{y}) \begin{pmatrix} u-p\\ v-w \end{pmatrix} + l \\ &= \begin{pmatrix} (v-w+w, -\nabla_x F(\bar{x}, \bar{y})(u-p) - \nabla_y F(\bar{x}, \bar{y})(v-w) + \nabla^2 (\bar{\lambda}^T q)(\bar{y})w + \tilde{l}) \\ &u-p+p \\ \end{pmatrix} \\ &= \begin{pmatrix} (v, v^*)\\ u \end{pmatrix}. \end{aligned}$$

This verifies (40) and then again (39) follows from Theorem 4. Theorem 3 now yields the assertion. \Box

REMARK 1. In Henrion et al. [11] the authors have derived (45) under the assumptions that $C = \mathbb{R}^n$, $\nabla_x F(\bar{x}, \bar{y})$ is surjective and MFCQ and CRCQ are fulfilled at \bar{y} . We conclude that this statement follows from Theorem 6 in a straightforward way.

REMARK 2. If $\overline{\mathcal{F}} = \overline{I}^+$, then span $\{\nabla q_i(\overline{y})^T \mid i \in \overline{I}^+\} = \overline{\mathcal{N}}^\perp$. If, in addition, $\nabla_y \mathscr{L}(\overline{x}, \overline{y}, \overline{\lambda})$ is positive definite on $\overline{\mathcal{N}}$, i.e., $v^T \nabla_y \mathscr{L}(\overline{x}, \overline{y}, \overline{\lambda}) v > 0$, $\forall 0 \neq v \in \overline{\mathcal{N}}$, then for every $v^* \in \mathbb{R}^m$ the generalized equation

$$0 \in \nabla_{\!_{\mathcal{V}}} \mathscr{L}(\bar{x}, \bar{y}, \bar{\lambda})v + v^* + \hat{N}_{\bar{\mathcal{N}}}(v)$$

has a solution; see, e.g., Outrata et al. [20, Theorem 4.6]. We conclude that in this case assumption (43) is fulfilled with $P = \{0\}$.

6. Applications.

6.1. Isolated calmness. A multifunction Ψ : $\mathbb{R}^d \rightrightarrows \mathbb{R}^s$ is said to have the *isolated calmness* property at $(\bar{u}, \bar{v}) \in \operatorname{gph} \Psi$, provided there exist neighborhoods \mathcal{U} of \bar{u} and \mathcal{V} of \bar{v} and a constant $\kappa \ge 0$ such that

$$\Psi(u) \cap \mathcal{V} \subset \{\bar{v}\} + \kappa ||u - \bar{u}||\mathbb{B} \text{ when } u \in \mathcal{U}.$$

In Levy [14], it has been proved that Ψ possesses the isolated calmness property at (\bar{u}, \bar{v}) if and only if

$$D\Psi(\bar{u},\bar{v})(0) = \{0\}; \tag{46}$$

cf. also Dontchev and Rockafellar [5, Theorem 4C.1].

This result has been applied in Henrion et al. [10, Theorem 4.1] to the solution map S given by (4). On the basis of Theorem 1 the latter result can be substantially generalized.

THEOREM 7. Let $(\bar{x}, \bar{y}) \in \text{gph}S$ and assume that M is metrically subregular at $(\bar{y}, 0)$ and metrically regular in the vicinity of \bar{y} . Then S has the isolated calmness property provided for all $v \in \mathbb{R}^m$ one has the implication

$$\left. \begin{array}{l} 0 \in \nabla_{\! y} \mathscr{L}(\bar{x}, \bar{y}, \lambda) v + \hat{N}_{\bar{K}}(v) \\ \lambda \in \bar{\Lambda}(v) \end{array} \right\} \Rightarrow v = 0.$$

$$(47)$$

Moreover, if $\nabla_x F(\bar{x}, \bar{y})$ is surjective, than (47) is not just sufficient but also necessary for S to have the isolated calmness property at (\bar{x}, \bar{y}) .

PROOF. By virtue of Rockafellar and Wets [26, Theorem 6.31] for all $h \in \mathbb{R}^n$

$$DS(\bar{x},\bar{y})(h) \subset \left\{ v \in \mathbb{R}^m \mid 0 \in \nabla_x F(\bar{x},\bar{y})h + \nabla_y F(\bar{x},\bar{y})v + D\hat{N}_{\Gamma}(\bar{y},-F(\bar{x},\bar{y}))(v)) \right\}.$$
(48)

The first assertion thus follows from the combination of (46), (48), and Theorem 1.

The second assertion follows from the fact that inclusion (48) becomes equality whenever $\nabla_x F(\bar{x}, \bar{y})$ is surjective; cf. Rockafellar and Wets [26, Exercise 6.32]. \Box

Note that in the setting of Theorem 3 condition (47) can be simplified and attains the form

$$0 \in \nabla_{\!v} \mathscr{L}(\bar{x}, \bar{y}, \lambda) v + \hat{N}_{\bar{K}}(v) \implies v = 0,$$

where $\bar{\lambda}$ is an arbitrary multiplier from $\bar{\Lambda}(v)$ for some nonzero $v \in \bar{K}$. The case when $\bar{K} = \{0\}$ is, of course, trivial.

EXAMPLE 5. Consider the GE

$$0 \in -x + \hat{N}_{\Gamma}(y) \tag{49}$$

with Γ given in Example 4. Let $\bar{x} = (0, 1)$ and $\bar{y} = (0, 0)$ so that $\bar{y}^* = \bar{x}$, $\bar{K} = T_{\Gamma}(0) = \{v \mid v_1 \le 0, v_2 = 0\}$,

$$\bar{\Lambda} = \{\lambda \in \mathbb{R}^3_+ \mid \lambda_1 - \lambda_2 = 1, \, \lambda_3 = 0\}$$

and

$$\bar{\Lambda}(v) = \begin{cases} \{\lambda \in \bar{\Lambda} \mid \lambda_1 = 1, \lambda_2 = 0\} & \text{if } 0 \neq v \in \bar{K} \\ \bar{\Lambda} & \text{if } v = 0. \end{cases}$$

As in Example 4, all conditions of Theorem 3 are fulfilled and so we may invoke Theorem 7 and conclude that the left-hand side of (47) attains for nonzero v the form of the system

$$0 \in \begin{bmatrix} -2v_1 \\ 0 \end{bmatrix} + \mathbb{R} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$
$$v_1 \le 0, \qquad v_2 = 0.$$

This system clearly implies that v = 0 and so the solution map of GE (49) has the isolated calmness property at (\bar{x}, \bar{y}) . \triangle

6.2. S-stationarity conditions for MPECs. Consider the mathematical program with equilibrium constraints

$$\min f(x, y) \quad \text{subject to } 0 \in F(x, y) + \hat{N}_{\Gamma}(y), \quad x \in C,$$
(50)

where $f: \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}, F: \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}^m$ are continuously differentiable and $C \subset \mathbb{R}^n$ is a closed set.

THEOREM 8. Let (\bar{x}, \bar{y}) be a local solution of the MPEC (50). Suppose that the assumptions of Theorem 5 are fulfilled. Then there exists a MPEC multiplier w such that

$$0 \in \nabla_{\mathbf{x}} f(\bar{x}, \bar{y})^T + \nabla_{\mathbf{x}} F(\bar{x}, \bar{y})^T w + \hat{N}_C(\bar{x})$$
(51)

$$0 \in \nabla_{y} f(\bar{x}, \bar{y})^{T} + \nabla_{y} F(\bar{x}, \bar{y})^{T} w + \hat{D}^{*} \hat{N}_{\text{gph}\,\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^{*})(w),$$

$$(52)$$

where $\bar{y}^* := -F(\bar{x}, \bar{y})$. In particular we have $w \in -\bigcap_{v \in \bar{\mathcal{N}}} \bar{\mathcal{W}}(v)$ and

$$0 \in \nabla_x f(\bar{x}, \bar{y})^T + \nabla_x F(\bar{x}, \bar{y})^T w + \hat{N}_C(\bar{x})$$

$$0 \in \nabla_y f(\bar{x}, \bar{y})^T + \nabla_y F(\bar{x}, \bar{y})^T w + \bigcap_{v \in \bar{\mathcal{N}}} \bar{L}(v; -w)$$

PROOF. Follows from Theorem 5 combined with the standard optimality condition $0 \in \nabla f(x, y) + \hat{N}_{gph,\bar{S}}(\bar{x}, \bar{y})$. \Box

EXAMPLE 6. Consider the MPEC (50) with $x \in \mathbb{R}^3$, $y \in \mathbb{R}^3$,

$$f(x, y) = -x_1 - y_1 + \frac{1}{2}y_2^2 + y_3^2$$
, $F(x, y) = x$, $C = \{a \in \mathbb{R}^3 \mid a_1 \le -1\}$

and Γ from Example 2. We claim that the pair $(\bar{x}, \bar{y}) = ((-1, 0, 0), (0, 0, 0)) \in C \times \Gamma$ is a solution of this MPEC. Indeed, $-\bar{x} \in \hat{N}_{\Gamma}(\bar{y})$ by Example 2 and for any feasible pair (\tilde{x}, \tilde{y}) one has

$$f(\tilde{x}, \tilde{y}) \ge \inf_{\substack{x \in C \\ y \in \Gamma}} f(x, y) \ge \inf_{\substack{x_1 \le -1 \\ (y_2, y_3) \in \mathbb{R}^2}} \left(-x_1 + \frac{1}{2}y_2^2 + y_3^2 \right) = 1 = f(\bar{x}, \bar{y}).$$

Next, we verify the assumptions of Theorem 8. The required properties of the corresponding perturbation mapping M hold by virtue of MFCQ. Put $P = \{0\} \times \mathbb{R} \times \mathbb{R}$. Since $T_C(\bar{x}) = \mathbb{R}_- \times \mathbb{R} \times \mathbb{R}$, one has $T_C(\bar{x}) + P \subset T_C(\bar{x})$. Further, $\bar{y}^* = -\bar{x} = (1, 0, 0)$, $\bar{\Lambda} = \{\lambda \in \mathbb{R}^2_+ \mid \lambda_1 + \lambda_2 = 1\}$, $\bar{I}^+ = \{1, 2\}$ and so

$$\nabla_{x}F(\bar{x},\bar{y})P + \operatorname{span}\{\nabla q_{i}(\bar{y}) \mid i \in \bar{I}^{+}\} = (\{0\} \times \mathbb{R} \times \mathbb{R}) + (\mathbb{R} \times \{0\} \times \{0\}) = \mathbb{R}^{3}.$$

Note that $\mathscr{C} = \{(0,1), (1,0)\}$ and $N_C(\bar{x}) = \mathbb{R}^+ \times \{0\} \times \{0\}$. Hence for every $\lambda \in \mathscr{C}$ the conditions $\nabla F_x(\bar{x}, \bar{y})^T v \in N_C(\bar{x})$, $\nabla q_i(\bar{y})v = 0, i \in I^+(\lambda)$, amount to

$$(v_1, v_2, v_3) = \nabla F_x(\bar{x}, \bar{y})^T v \in N_C(\bar{x}) = \mathbb{R}^+ \times \{0\} \times \{0\}, \quad v_1 = 0$$

implying v = 0. Thus all conditions of Proposition 6 and also of Theorem 8 have been verified. As derived in Example 2,

$$\hat{N}_{\text{gph}\hat{N}_{\Gamma}}(\bar{y}, \bar{y}^{*}) = \bar{K}^{\circ} \times \{(0, 0, 0)\} = (\mathbb{R} \times \{0\} \times \{0\}) \times (0, 0, 0)$$

and so we may conclude that conditions (51), (52) are fulfilled with w = 0 and with the point (1, 0, 0) belonging to $\hat{D}^* \hat{N}_{\text{gph}\hat{N}_{r}}(\bar{y}, \bar{y}^*)(0)$. \triangle

7. Conclusion. It is well known that, in contrast to metric regularity and some other stability notions, the property of metric subregularity at a point does not carry over to a neighborhood. This lack of stability does not cause any troubles in the first-order nonsmooth calculus, where qualification conditions based on metric subregularity have been developed for all basic calculus rules; cf. Ioffe and Outrata [12]. In the second-order calculus, however, more stable qualification conditions are needed. One typically uses a surjectivity/ nondegeneracy assumption (Mordukhovich and Outrata [17, 18]) or at least MFCQ. In this paper, we suggest in this context to require, in addition to the metric subregularity, the metric regularity in the vicinity of the point in question introduced in Definition 2. At the first glance this combination may look somewhat cumbersome, but it turns out that at least in some second-order calculations (like the computation of generalized derivatives of the normal-cone mapping) it can very well be used. Moreover, as shown by examples, there are indeed realistic situations in which this combined property holds.

After completing this paper, some of the results were successfully applied to characterize tilt stability in nonlinear programming in the very recent paper by Gfrerer and Mordukhovich [8]. Thereby it was observed that the assumption of metric regularity in the vicinity of \bar{y} can be weakened by the so-called *bounded extreme point* property, which is not only implied by SOSCMS but also, e.g., by CRCQ; see Gfrerer and Mordukhovich [8, Proposition 3.4]. In fact, by carefully checking the proof of Theorem 1, one can see that the assumption of metric regularity in the vicinity of \bar{y} can be replaced by the requirement, that for all sequences $(t_k) \downarrow 0$, $(v_k) \rightarrow v$ and $(v_k^*) \rightarrow v^*$ such that $\bar{y}^* + t_k v_k^* \in \hat{N}_{\Gamma}(\bar{y} + t_k v_k)$ there exists a bounded sequence of multipliers (λ^k) with $\lambda^k \in \hat{N}_{\mathbb{R}^l_{-}}(q(\bar{y} + t_k v_k))$ and $\nabla q(\bar{y} + t_k v_k)^T \lambda^k = \bar{y}^* + t_k v_k^*$ for each k. In Gfrerer and Mordukhovich [8], this requirement is ensured via the bounded extreme point property.

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